



Symmetric Maneuver Loads Module Development & Integration within an Aircraft Tracking Environment

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Phoenix Integration Workshop

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Transition Success Story:

Stick-to-Stress Real-time Simulator (StS-RtS) Applied to F-15C/D

U.S. AIR FORCE

Background

- Clearly established need for more accurate & rapid analysis tools to manage cracking in legacy aircraft
- Using aircraft past their design service life leads to:
 - Unexpected new cracking locations
 - Requirement for extensive re-analysis
 - More frequent inspections; Longer depot visits
 - Mishaps, Fleet groundings
- AFRL-VA-WP-TR-1999-3037: The overwhelming type of problem encountered w/ F-15 is Excessive Dynamic Load**

Objectives

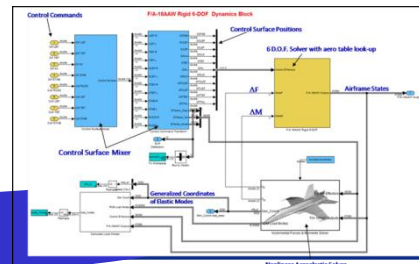
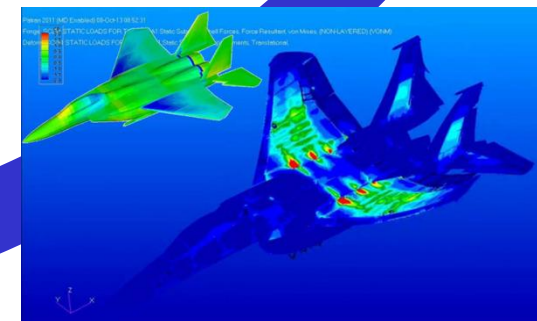
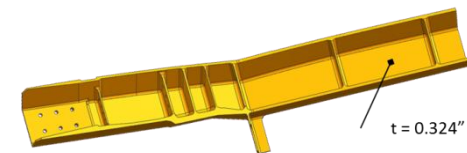
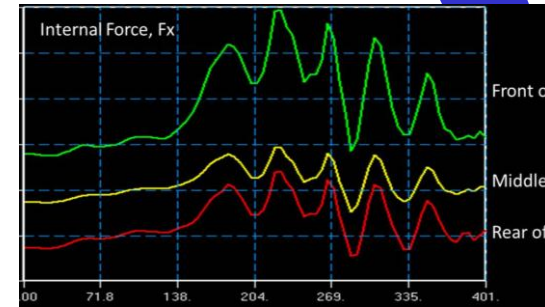
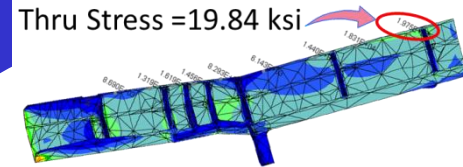
- Deliver improved accuracy F-15C/D Simulator
- Provide SPO with engineering analysis for use in assessment of a known cracking problem
- Provide F-15 program with an improved tool for Crisis Management, Service Life Extension Programs & ASIP use

Transitions

- Small Non-Recurring Expense to build for each Fleet/Block
- Delivered F-15C/D StS-RtS to AFRL's ADT Spiral I Program
- Reduces risk for other platforms

Remaining Useful Life via Dynamic Internal Loads On Critical Components

Thru Stress = 19.84 ksi





Motivation

- **USAF F-15C/D aircraft need to remain operational until 2025**
- **Lead the fleet aircraft have reached over 10,000 flight hours – exceeds the 8,000 FH design life**
- **Air National Guard mishap in Nov 2007 grounded the fleet**
- **The fleet was eventually cleared for flight**
- **However, concern remains regarding risks as the fleet continues to age**
- **New technology is absolutely necessary for the continued economic operation of the fleet**





Stick-to-Stress



- What is it?
 - A Physics Preserving, Real-time 6-DOF Simulation Tool for an Aeroelastic Vehicle, from Pilot Input to Global Airframe Stress
 - Includes Sensors, Control Surface Freeplay and Gust
- Why is it here?
 - Generate Comprehensive Representative Dynamic Stress Histories
- What else is it?
 - Prototype Development, Pilot Training, CLAW Evaluation
- **Preserve Individuality, then apply
Uncertainty Quantification**



SOA vs. MODSDF-StS



- SOA:
 - Quasi-steady, empirical, stress-transfer functions (STF)
 - Expensive to create, utilize and modify
 - New “hot spots” only from field
 - Curve-fit the curve-fit, usage severity amplification factors
- MODSDF-StS:
 - Dynamic, physics-based global stresses
 - Component Load comparison (dynamics included)
 - Quick comparison for original 16 (and re-fit) location STF
 - ID global hot-spots using direct dynamic stress
 - DADT FEM “cut-outs” of these global hot-spots



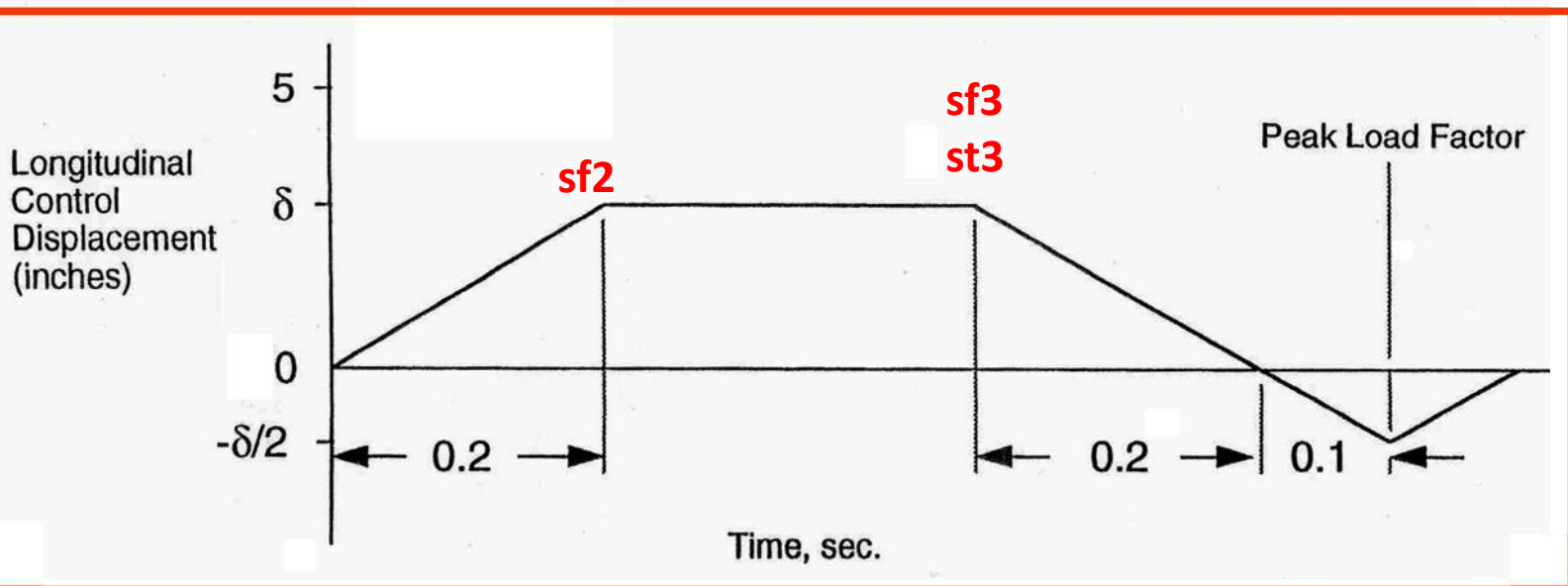
Mil-Spec Maneuvers



Symmetric Maneuvers

Abrupt Maneuvers (continued):

(c) By a control movement resulting in a ramp type displacement time curve as illustrated by the solid lines of the figure below. The duration of the maneuver and the control displacement δ will be just sufficient to attain the specified load factor coincidentally with the attainment of minus one-half δ .



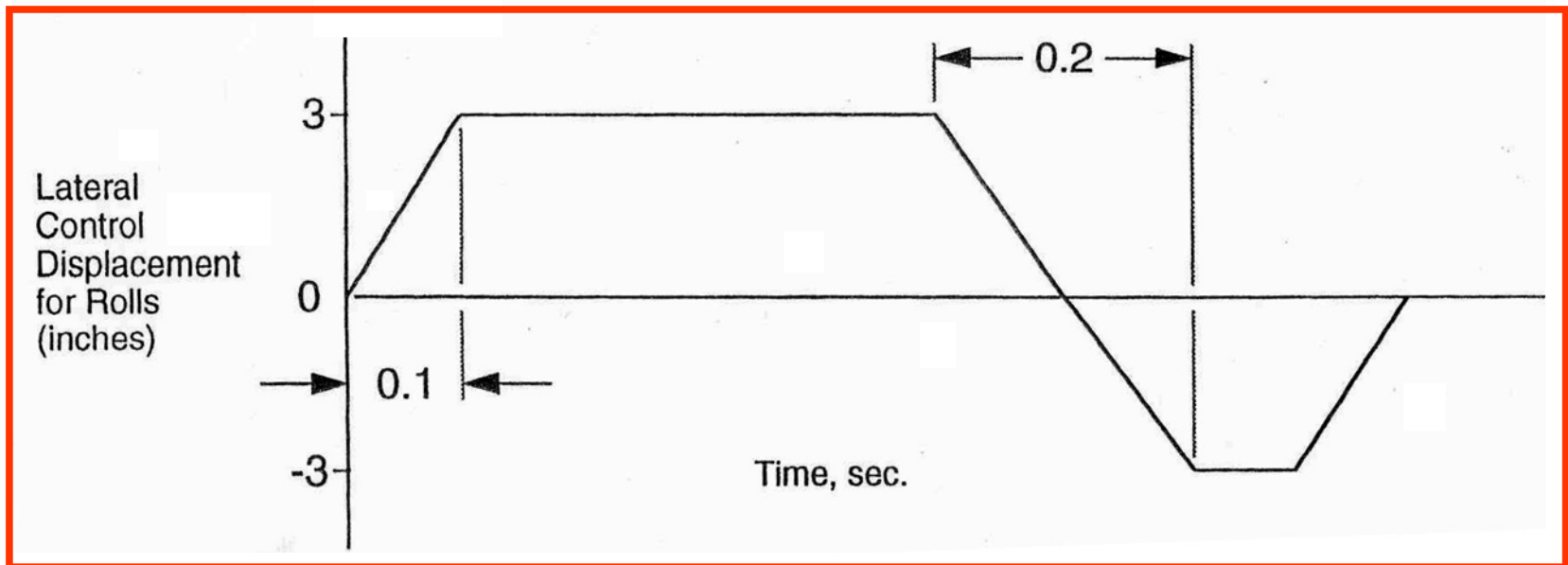


Mil-Spec Maneuvers



Unsymmetrical Maneuvers

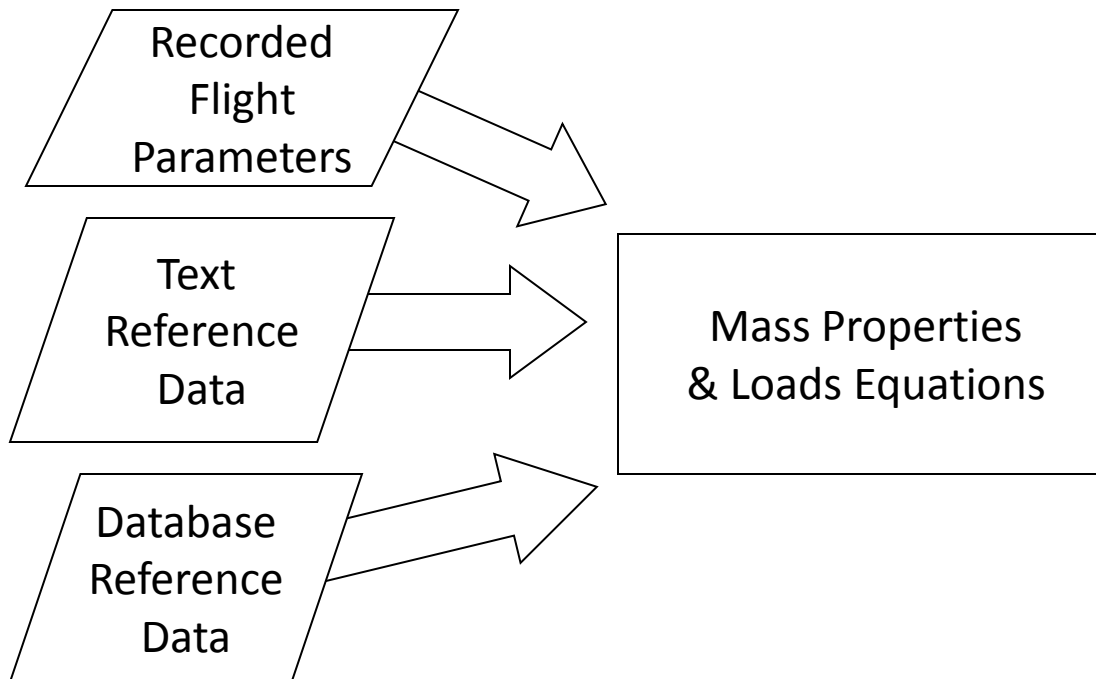
Rolling Maneuvers





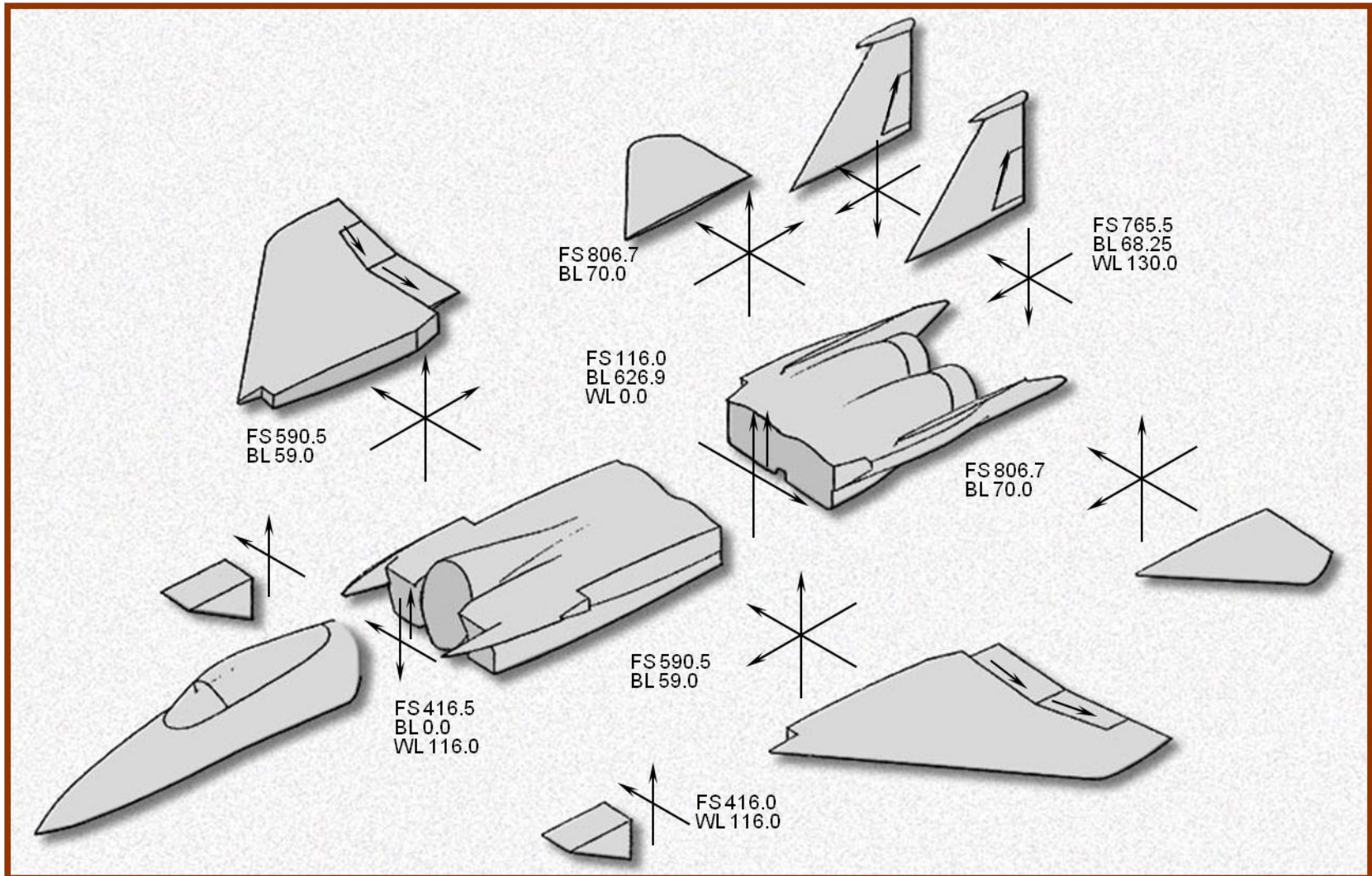
Component Loads

- Loads are calculated using equations involving reference data and recorded flight parameters





Component Loads





Component Loads



- Component loads are load summations at 'control' points which are usually the manufacturing splice points.
- Component loads can more easily be analytically derived.
- Component loads can be directly measured in the wind tunnel and in flight test.

$$BENDING = \left\{ C_{bending_{A_{\alpha A}}} + \frac{C_{bending}}{\delta_{Aileron}} \times \boxed{\delta_{Aileron}} \right\} \times \frac{C_{bending}}{P} \times \frac{\boxed{P_{(rad/sec)}} \times b_{ref}}{2 \times \boxed{VT_{(ft/sec)}}} \times S_{ref} \times \boxed{DP} \times C_{ref}$$

Roll Rate
↓
Aileron Deflection True Airspeed Dynamic Pressure



Stress Transfer Functions



- Component Loads and Airframe States are used as “Curve Fitting” inputs for Stress Transfer Functions

$$(C_1 * L_1 + C_2 * L_2 + C_3) * C_4$$

L_n are Loads (forces or moments)

C_n are regression constants

- Example: MSLUGL – Left main spar lower lug

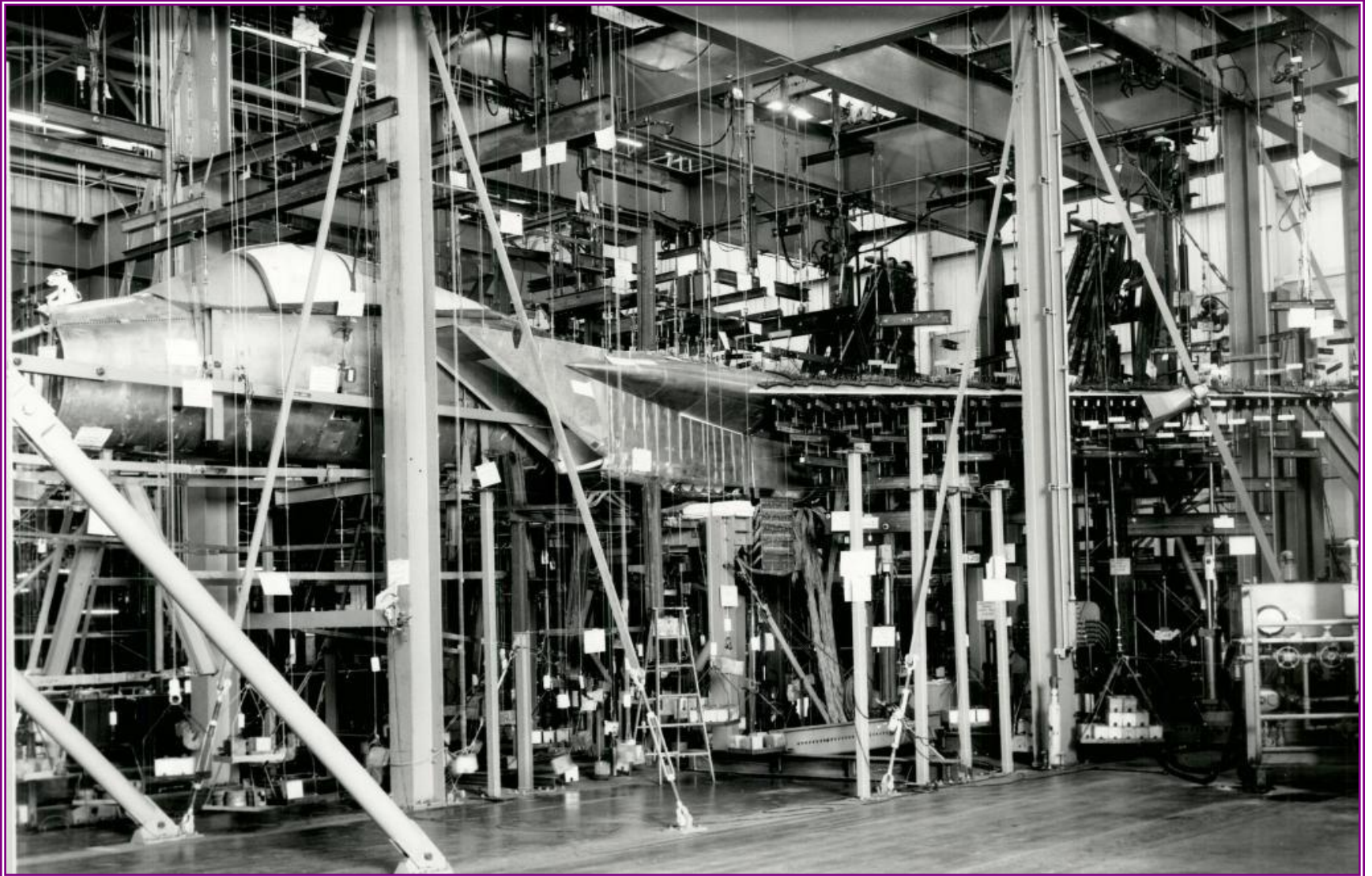
$$mslug = (2.9856E - 7 * iw bml - 9.8864E - 6 * iw sl - 1.9911E - 5) * 16.7E3$$

Left inner wing
bending moment

Left Inner
wing shear

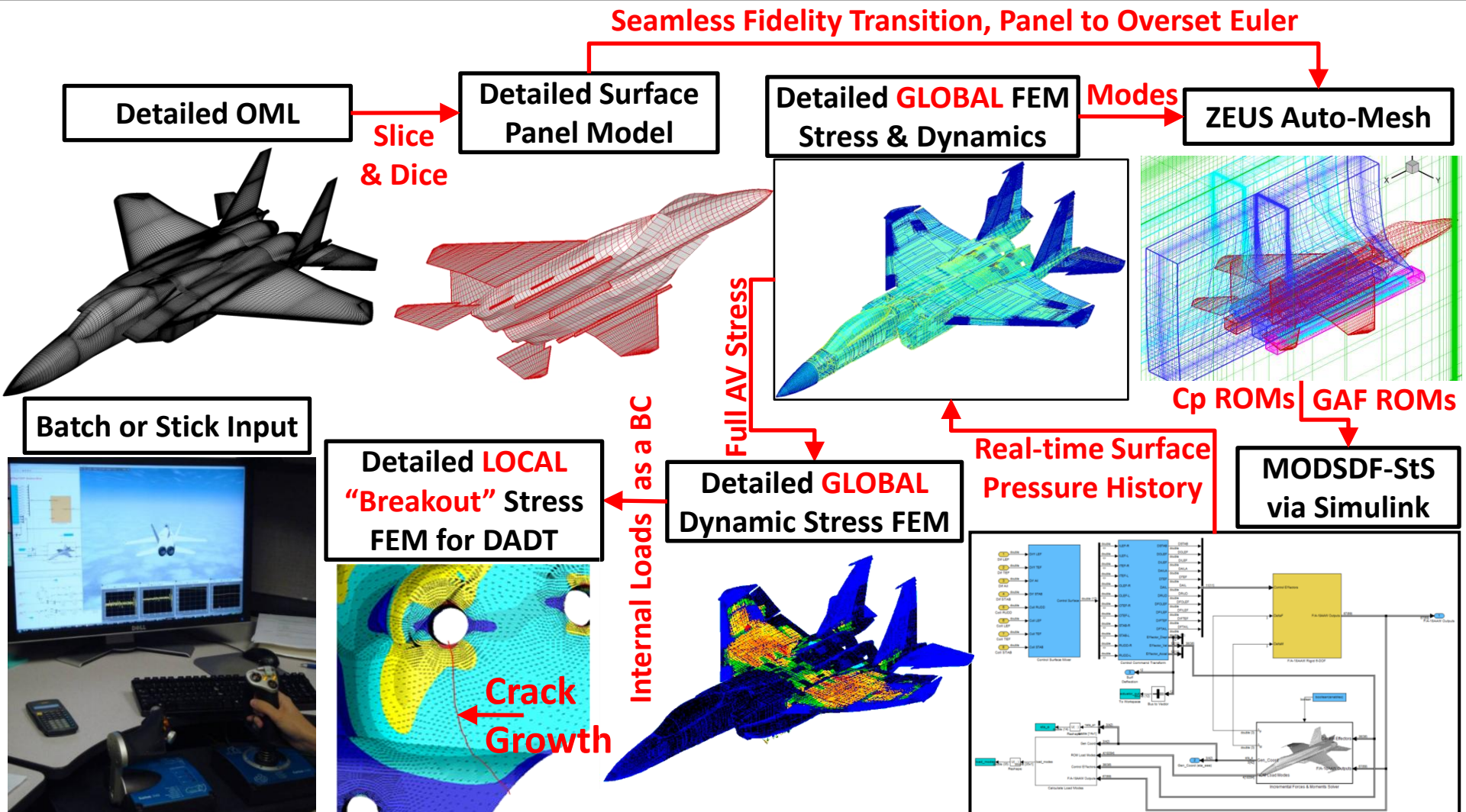


Fatigue Life Testing





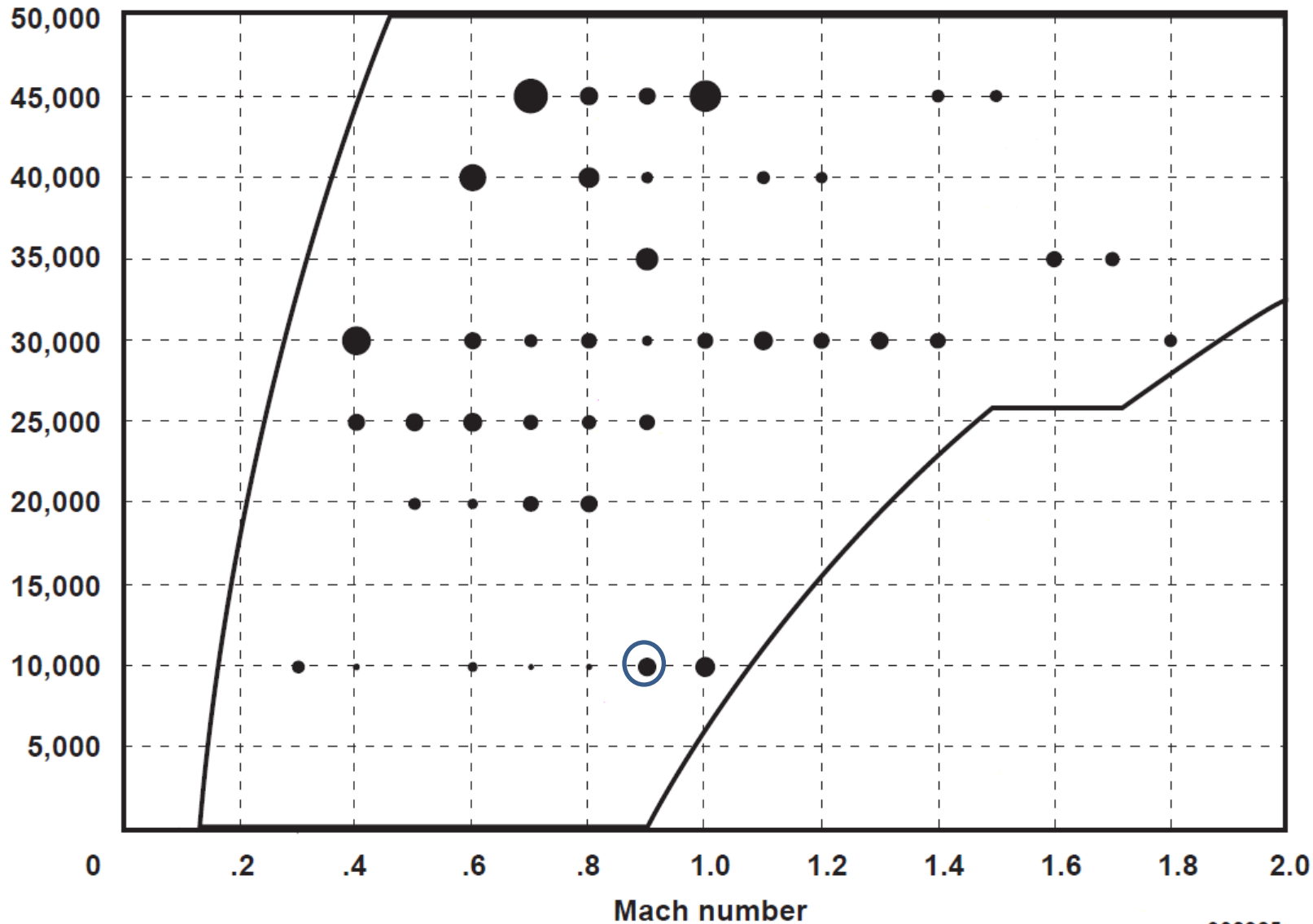
StS-RtS Process Overview



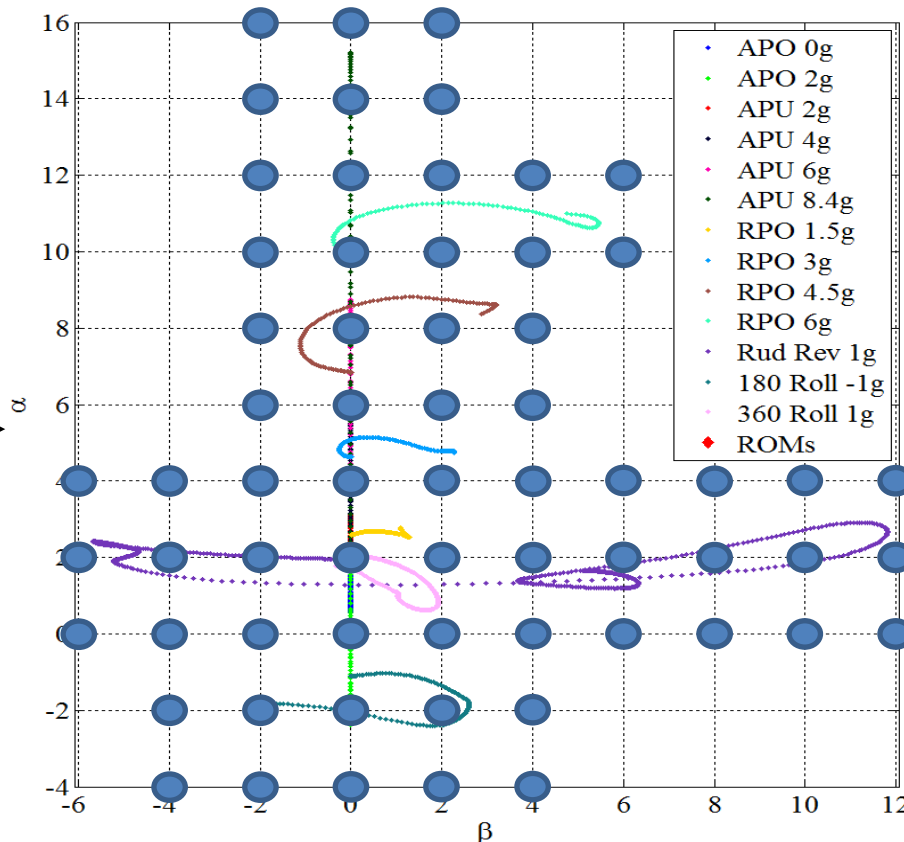
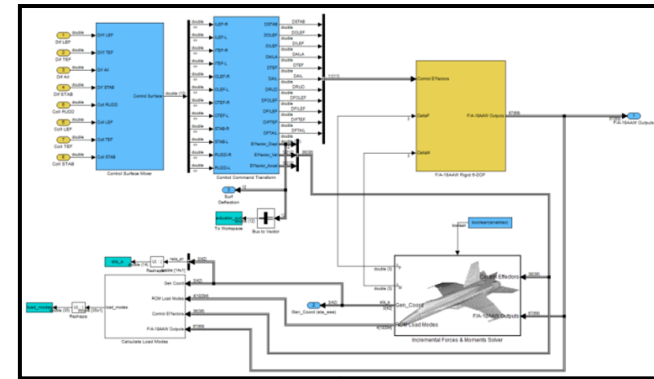
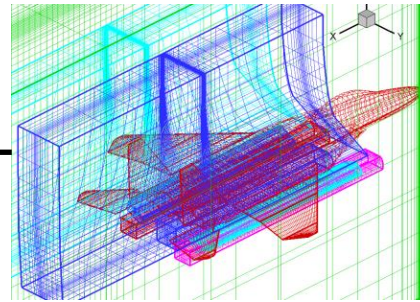
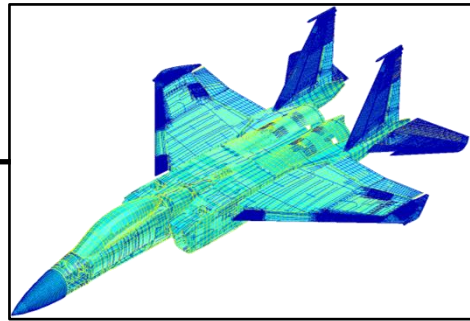
Detailed Mission-Vehicle-Pilot-Specific Dynamic Stress Histories for Fatigue, DADT & Fleet Management Purposes, all via Real-time Euler-based Simulation



For each Point in Flight Envelope ...



... Build ROMs and put in Simulator



For each Mach-Altitude "point-in-the-sky", there is an alpha-beta ROM matrix



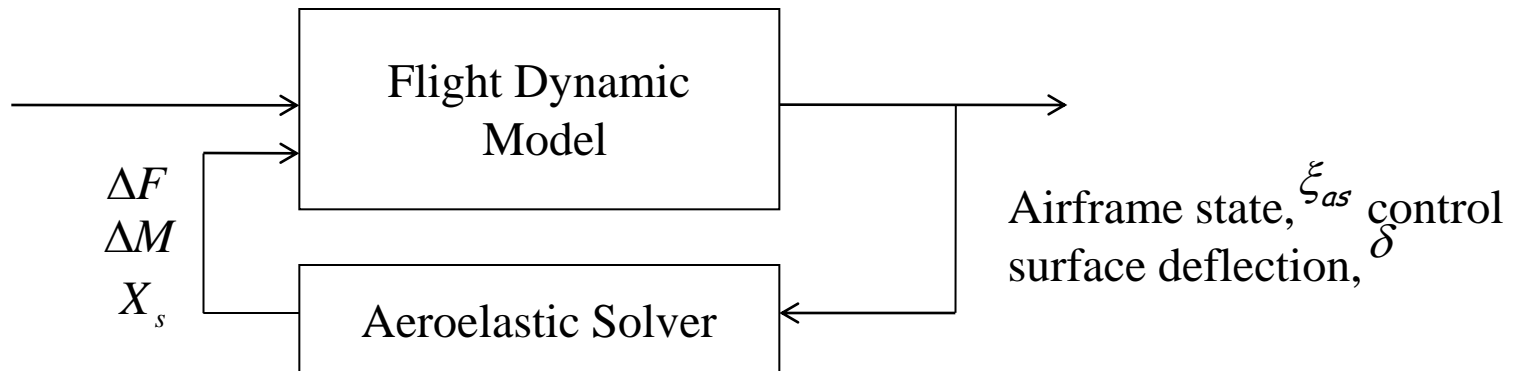
Approach, 6-DOF Compatibility



- Incorporates the add-on incremental forces and moments, ΔF and ΔM , due to aeroelastic effects in the nonlinear flight simulation model.

$$m \left[\dot{V}_b + \Omega_b \times V_b - T_{be} g_e \right] = F_{ext} + \Delta F$$
$$I_b \dot{\Omega}_b + \Omega_b \times I_b \Omega_b = M_{ext} + \Delta M$$

- Adds the structural oscillation, X_s , at the sensor locations to the sensor reading of rigid body motion.
- Modifies the linear aeroelastic equations of motion as an aeroelastic solver to provide ΔF , ΔM , and X_s at each time step in the nonlinear flight simulation model.





Integration of Flight Dynamic Model and Nonlinear Aeroelastic Solver



Control Commands

F/A-18AAW Rigid 6-DOF Dynamics Block

Control Surface Positions

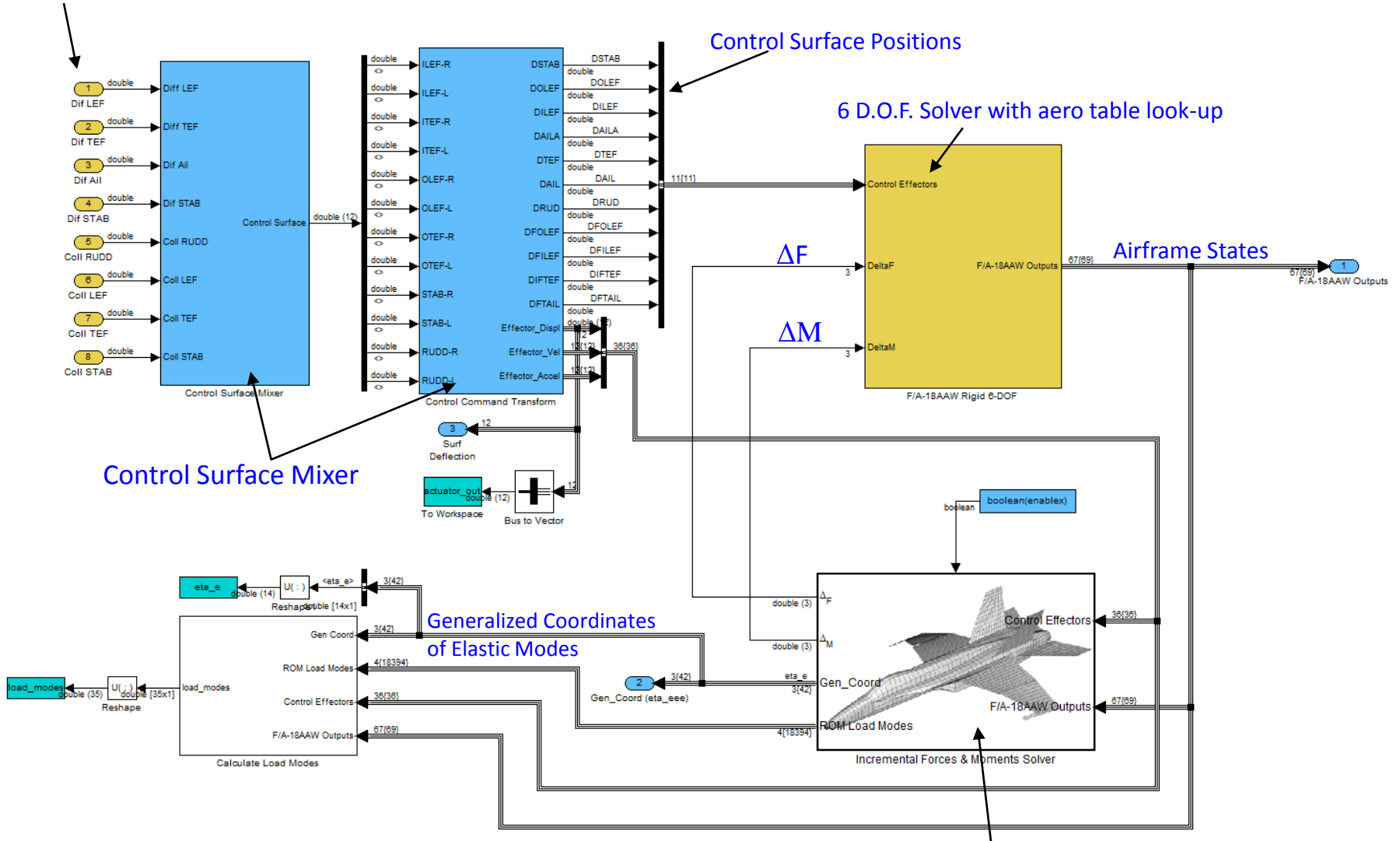
6 D.O.F. Solver with aero table look-up

Airframe States

Control Surface Mixer

Generalized Coordinates of Elastic Modes

Nonlinear Aeroelastic Solver





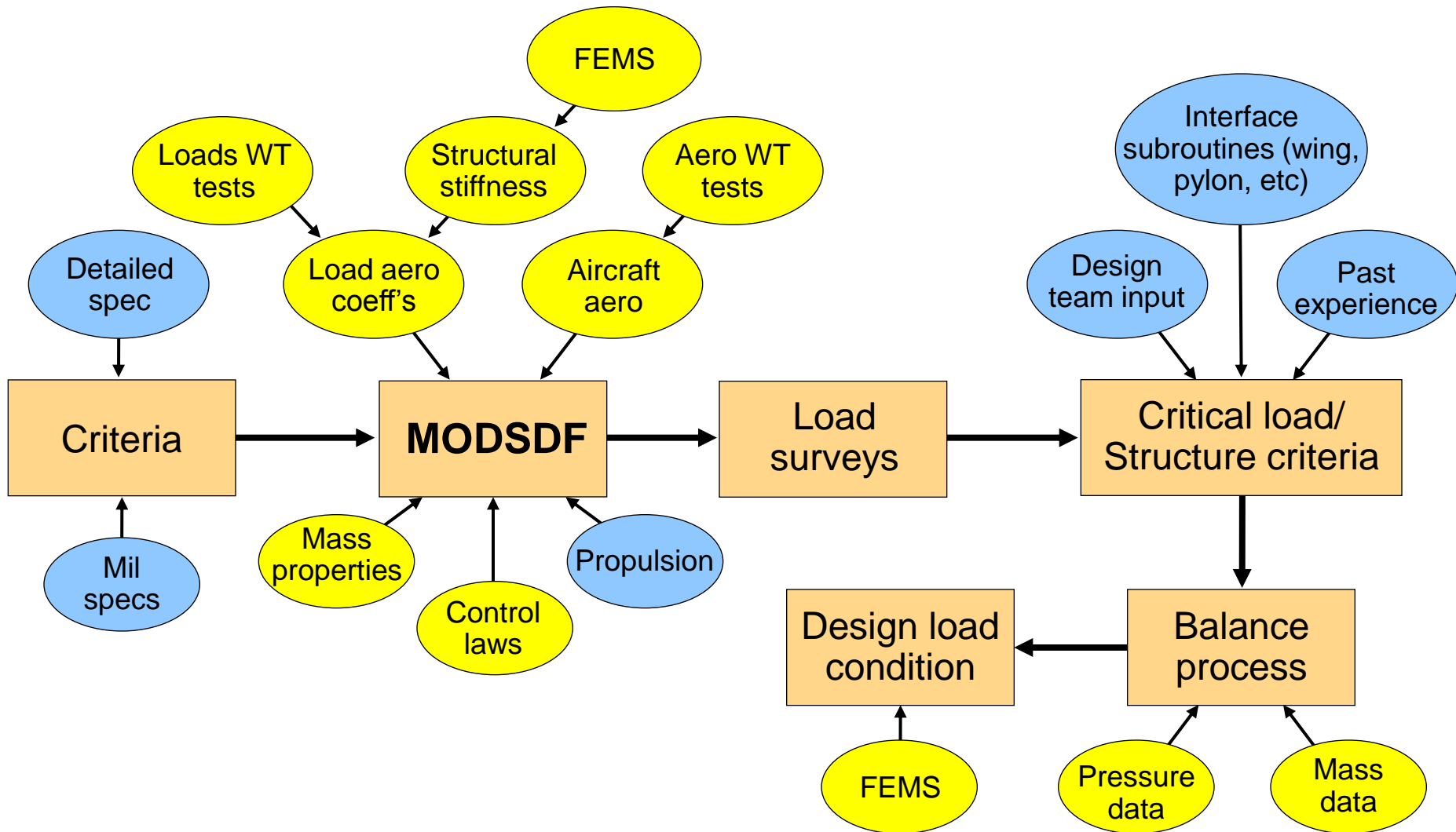
MODSDF (Modular Six Degree of Freedom) Overview



- **MODSDF predicts the trajectory and attitude of a vehicle in three dimensional space**
 - A high fidelity, non-linear, stand-alone, simulation of vehicle motion that employs a fixed-step fourth-order Runge-Kutta integration scheme and six DOF algorithm
 - Structure allows project-specific analysis requirements to be incorporated while preserving the integrity and generic quality of its embedded methods
 - » For example: Named pipes
- **Typical uses in St. Louis**
 - Evaluations of Flight Control System Designs
 - Time-Dependent Flying Qualities and Performance Characteristics
 - Flight, Store, and Ground Loads
 - Weapons Separation Characteristics
 - Verification of Manned Simulator Models
 - Reproduction of Flight Anomalies for Incident/Accident Investigations

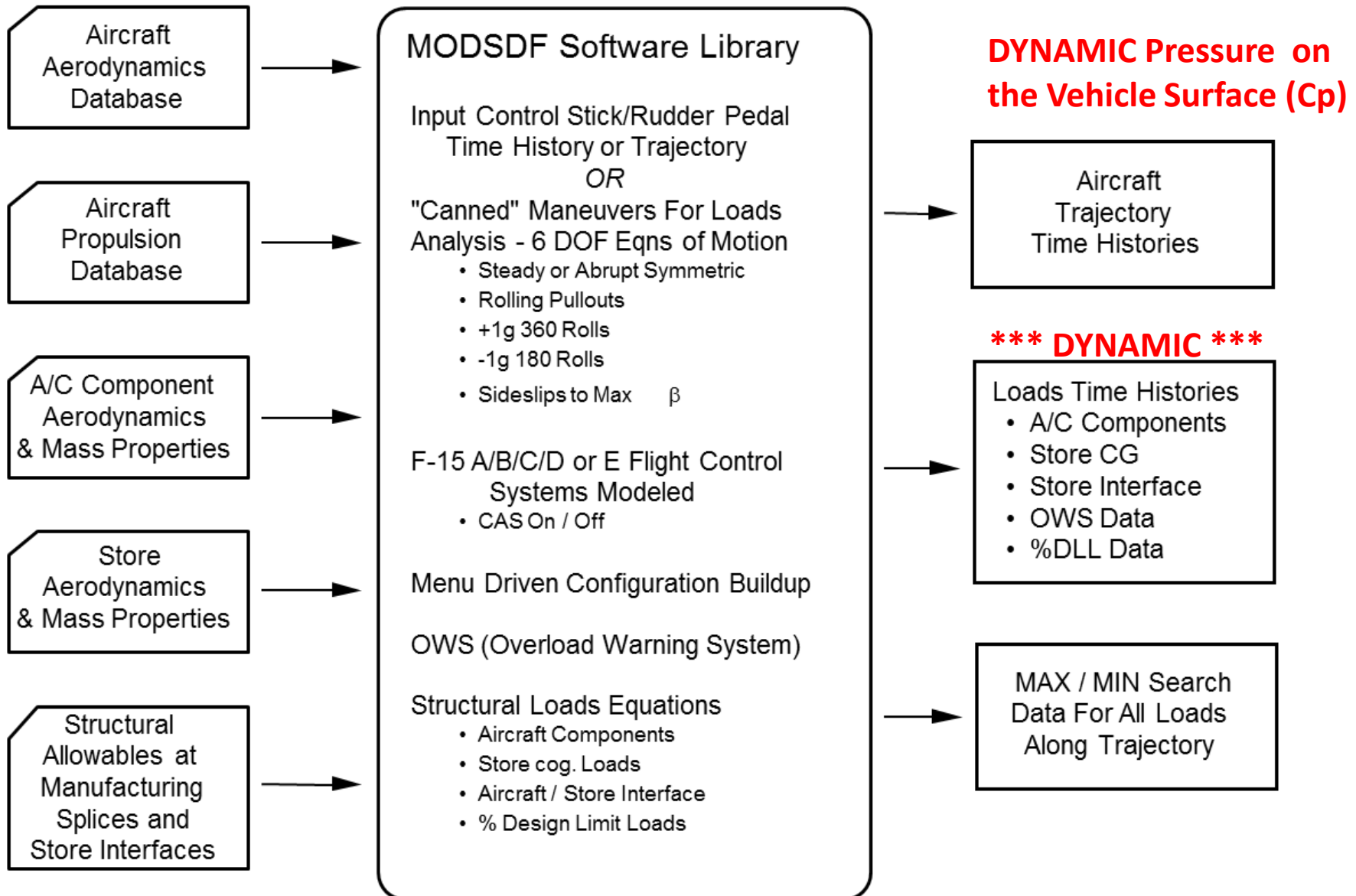


MODSDF-StS "Impacts"



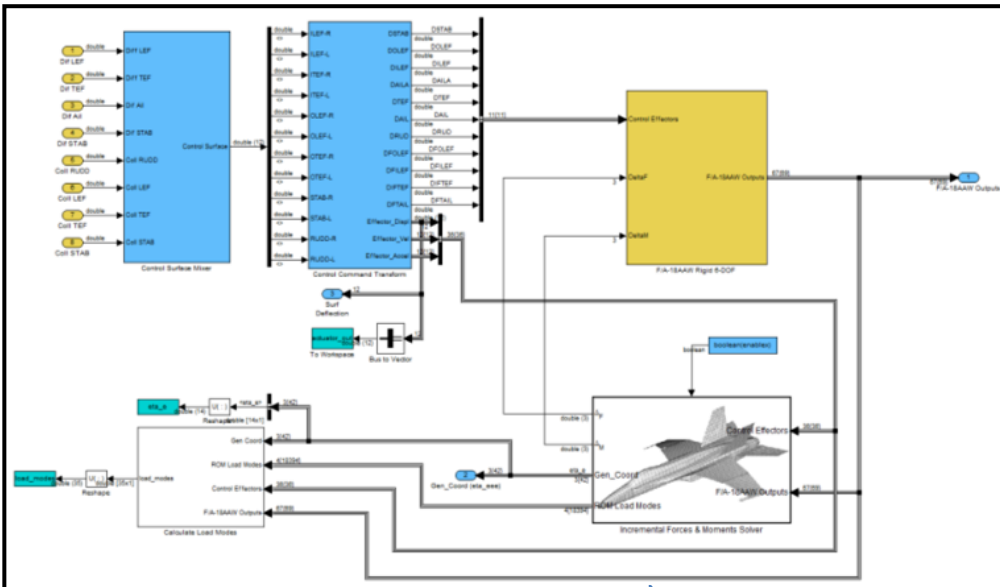


MODSDF Overview (StS)





MODSDF-StS to OFLCP & FDTS



Quasi-Static Component Loads
Dynamic Vehicle States

OFF

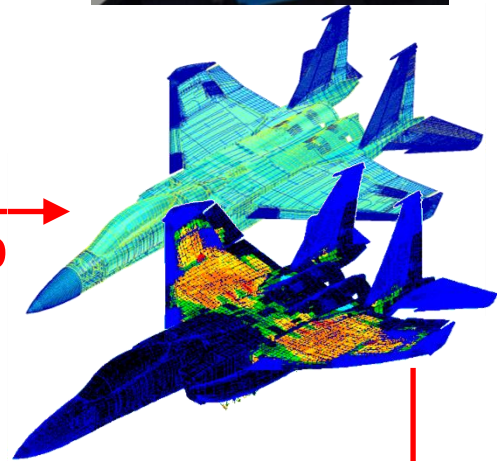
OFLCP-QS

GAF ROMs
 $\Delta F, \Delta M$



ON

C_p

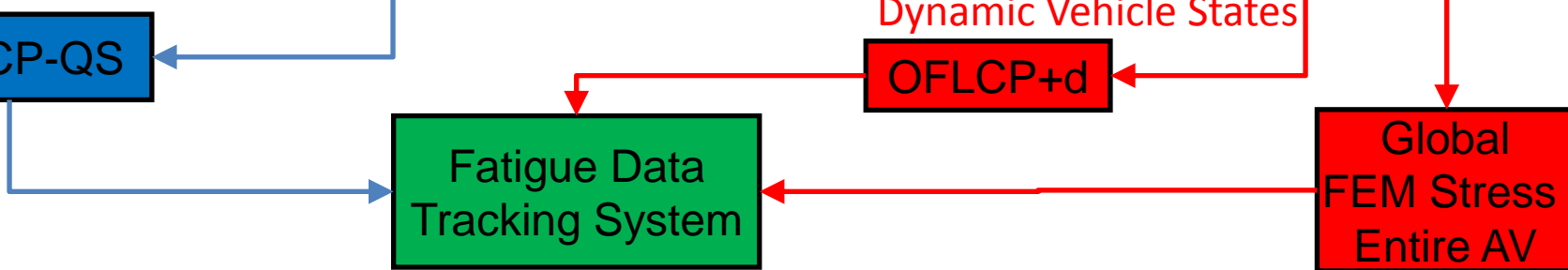


Dynamic Component Loads
Dynamic Vehicle States

OFLCP+d

Fatigue Data Tracking System

Global FEM Stress Entire AV

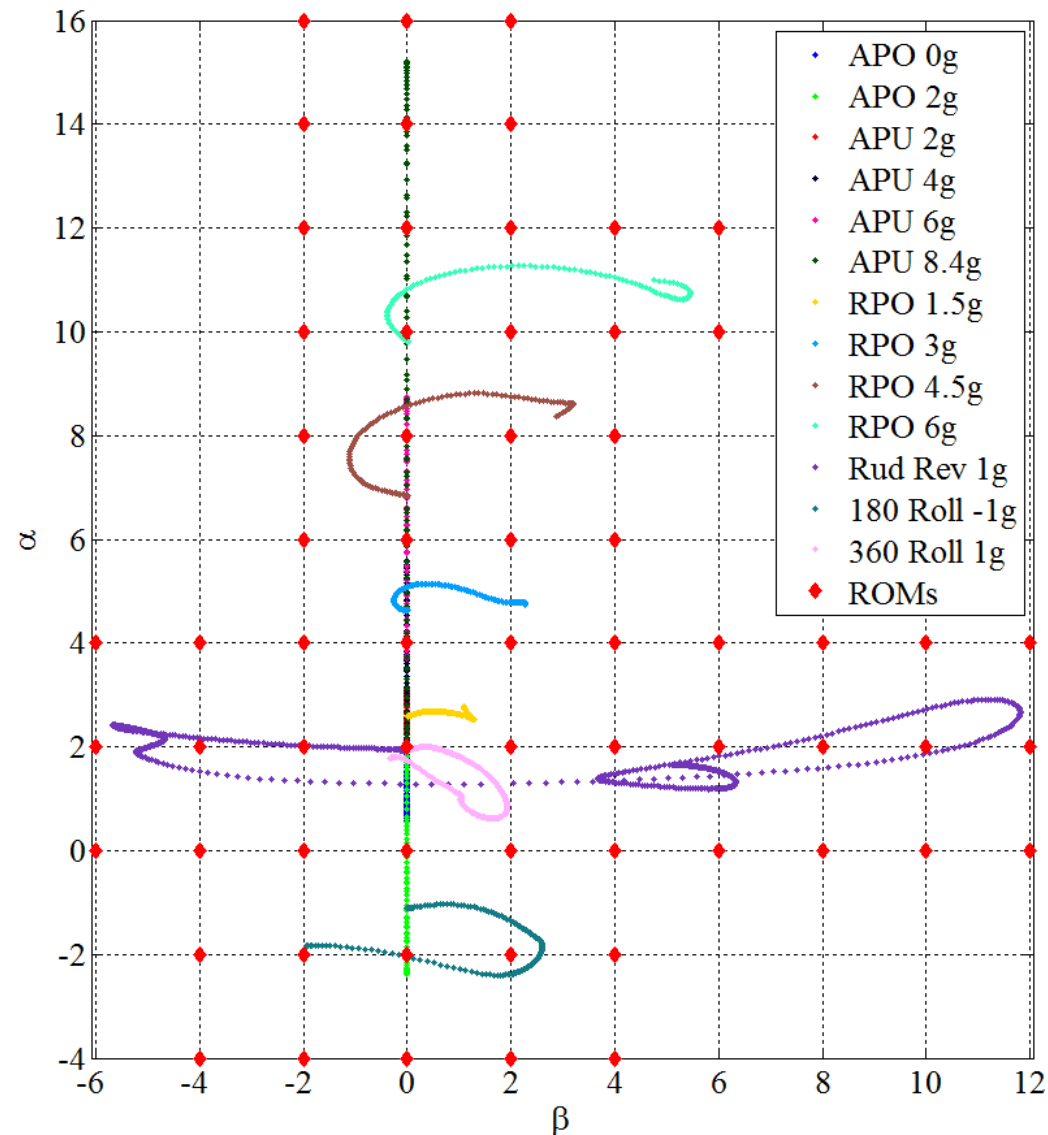




ROM Flight Conditions



- α/β traces for maneuvers performed in MODSDF at Mach 0.95, 15kft
- Need an aeroelastic ROM at each α/β pair marked by a red diamond
- For APO/APU maneuvers only $\beta=0$ ROMs required
- APU 4g maneuver requires $\alpha=0, 2, 4, 6$ ROMs, for example

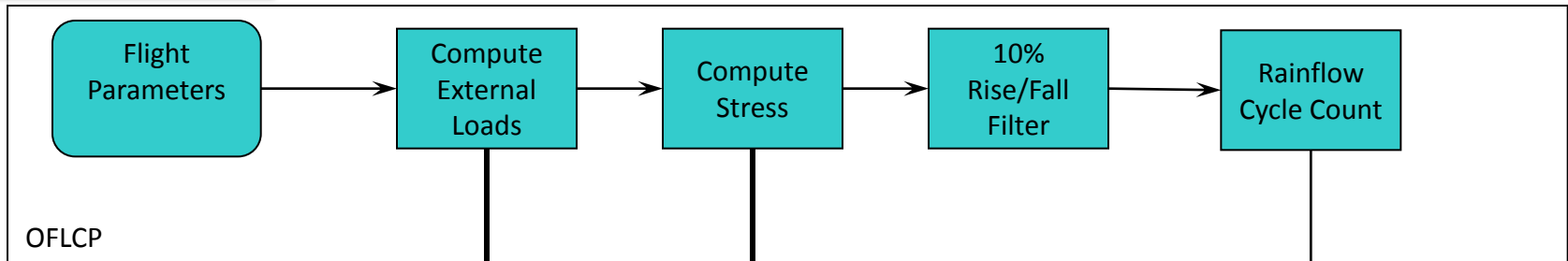




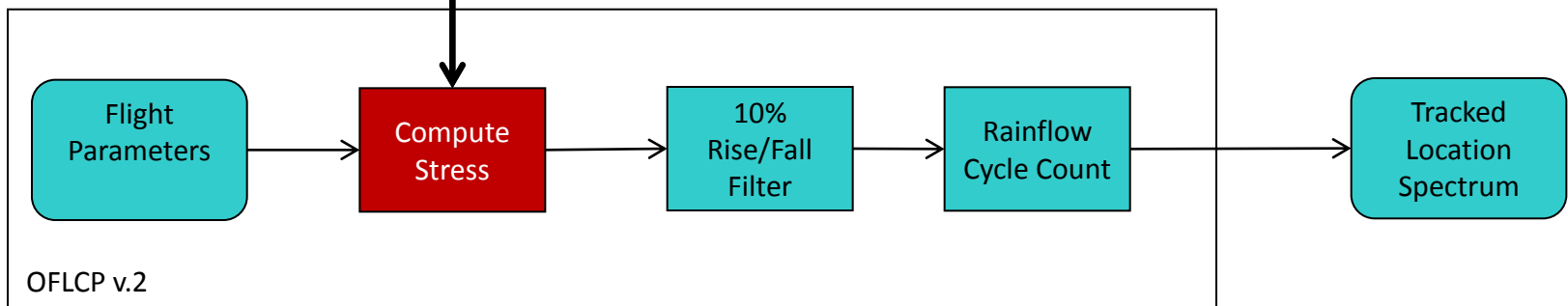
Spectrum Development: Option 2 – Revise the Process



Current Process:



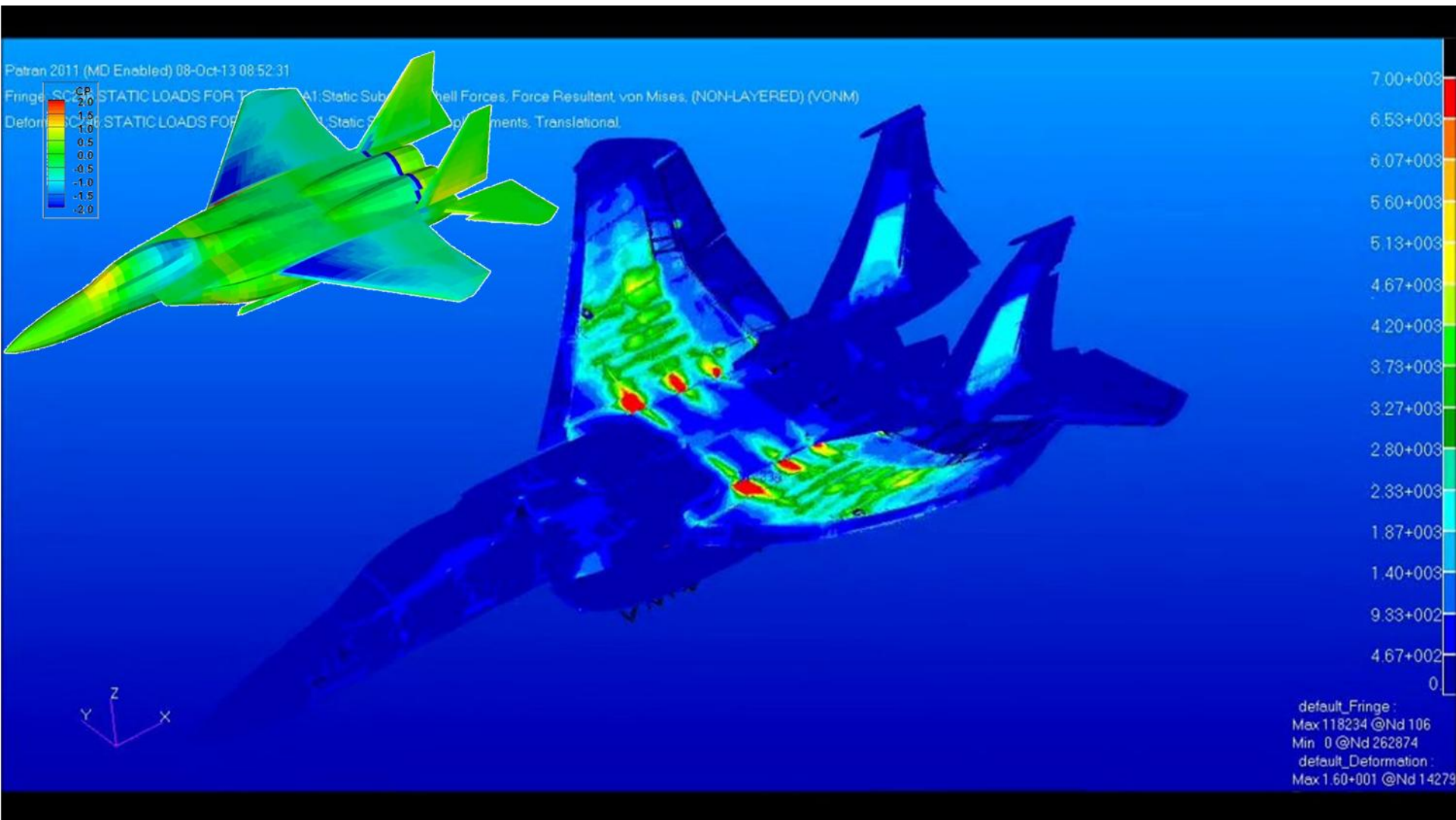
Revised StS Process: Option 2



Direct calculation of stress spectrum for any fatigue critical location

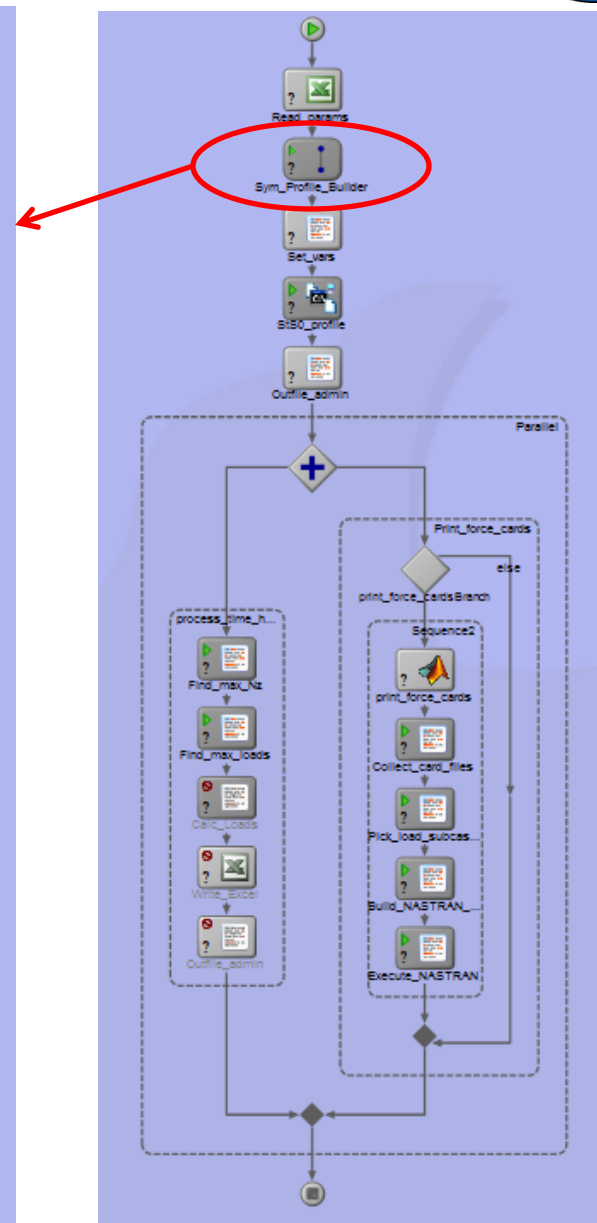
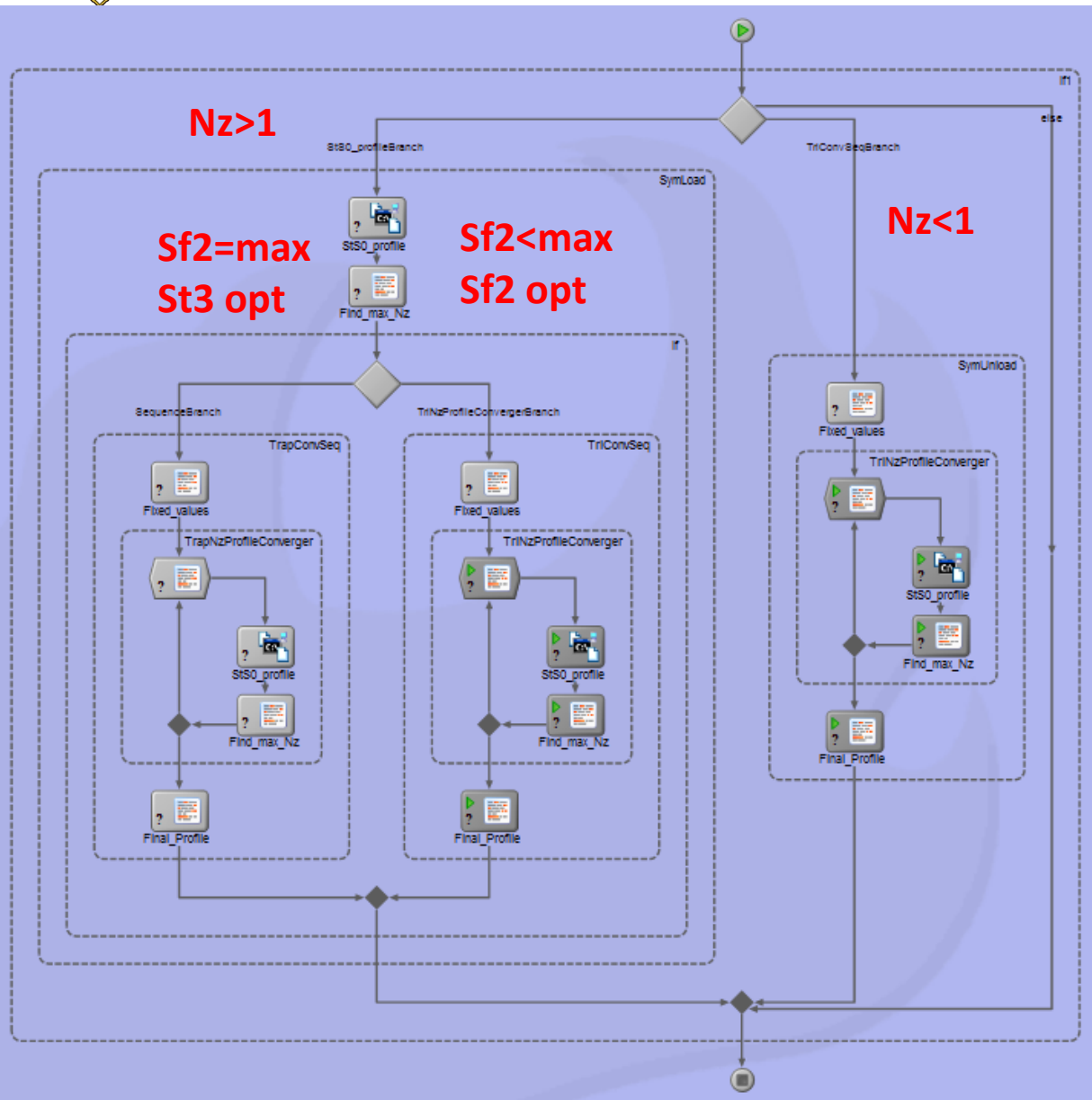


Beyond Component Loads



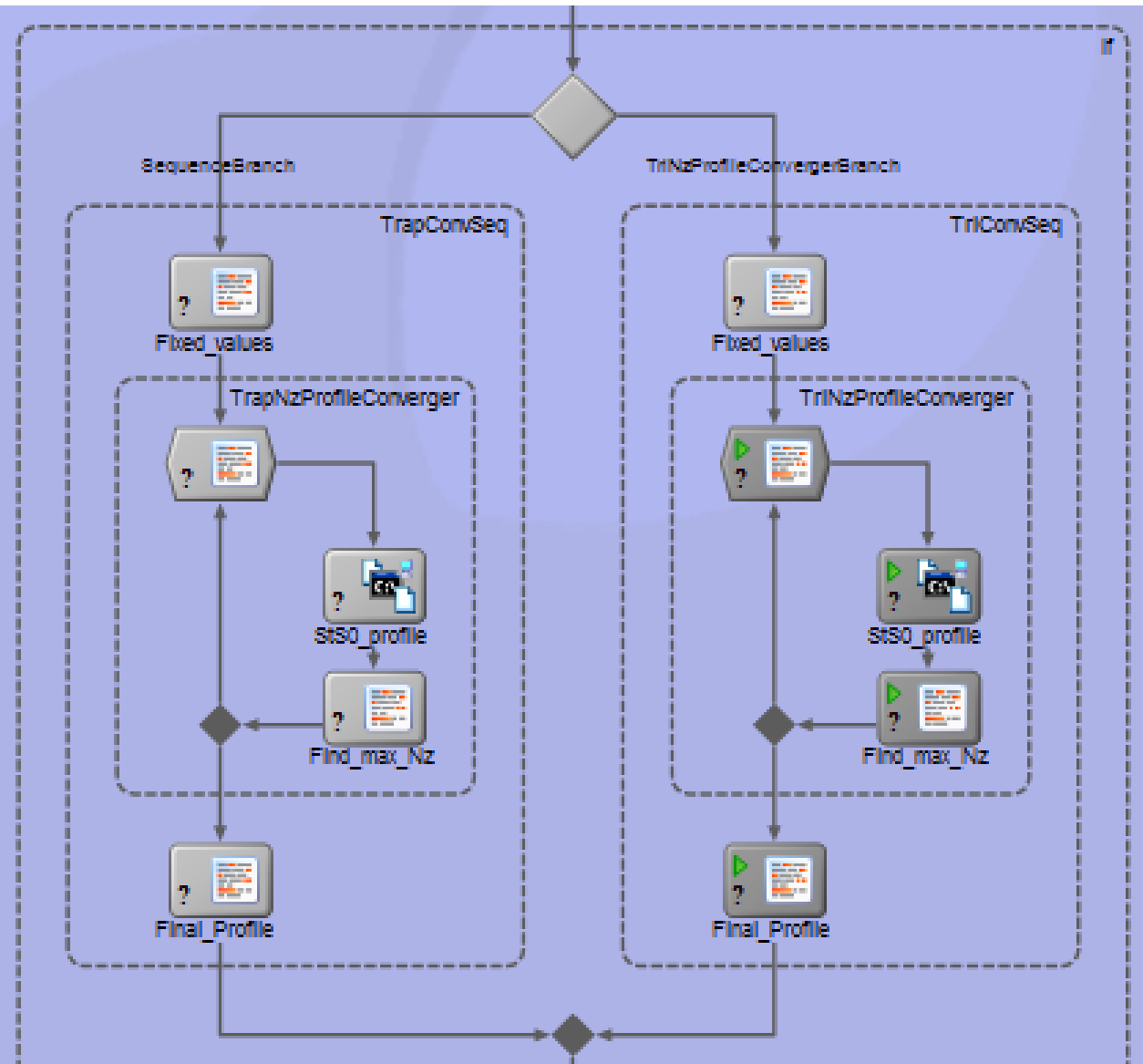


The Process in Model Center





The Process in Model Center





The Process in Model Center



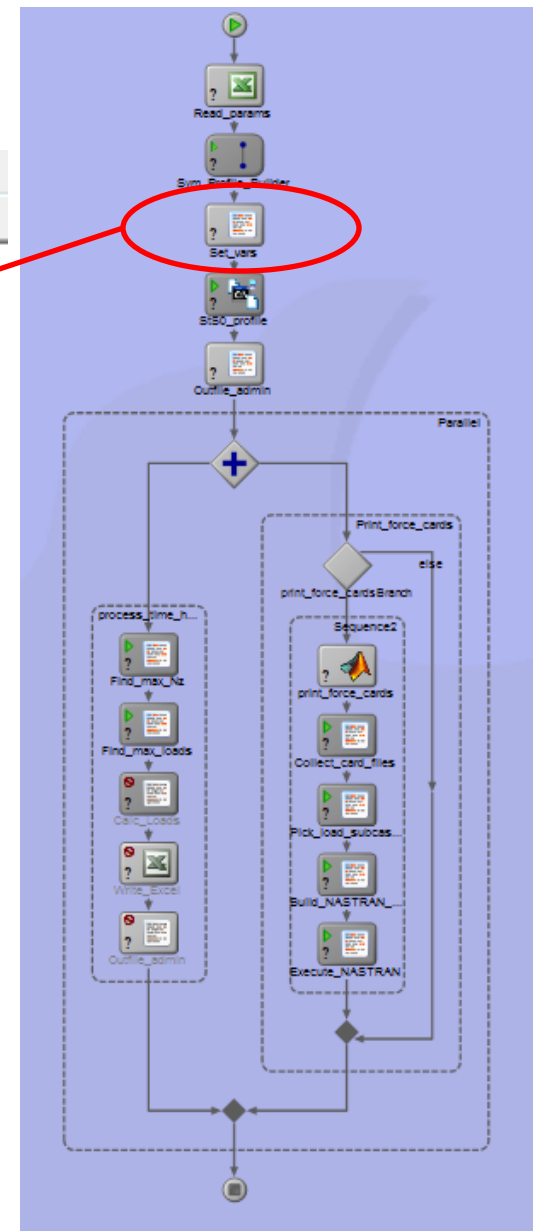
ModelCenter Variables

- Set_vars
 - st3list[]
 - sf2list[]
 - sf3list[]
 - ICFLAG
 - TgtNzlist[]
 - TgtNz
 - st3
 - st4
 - sf2
 - sf3

<click to add variable...>

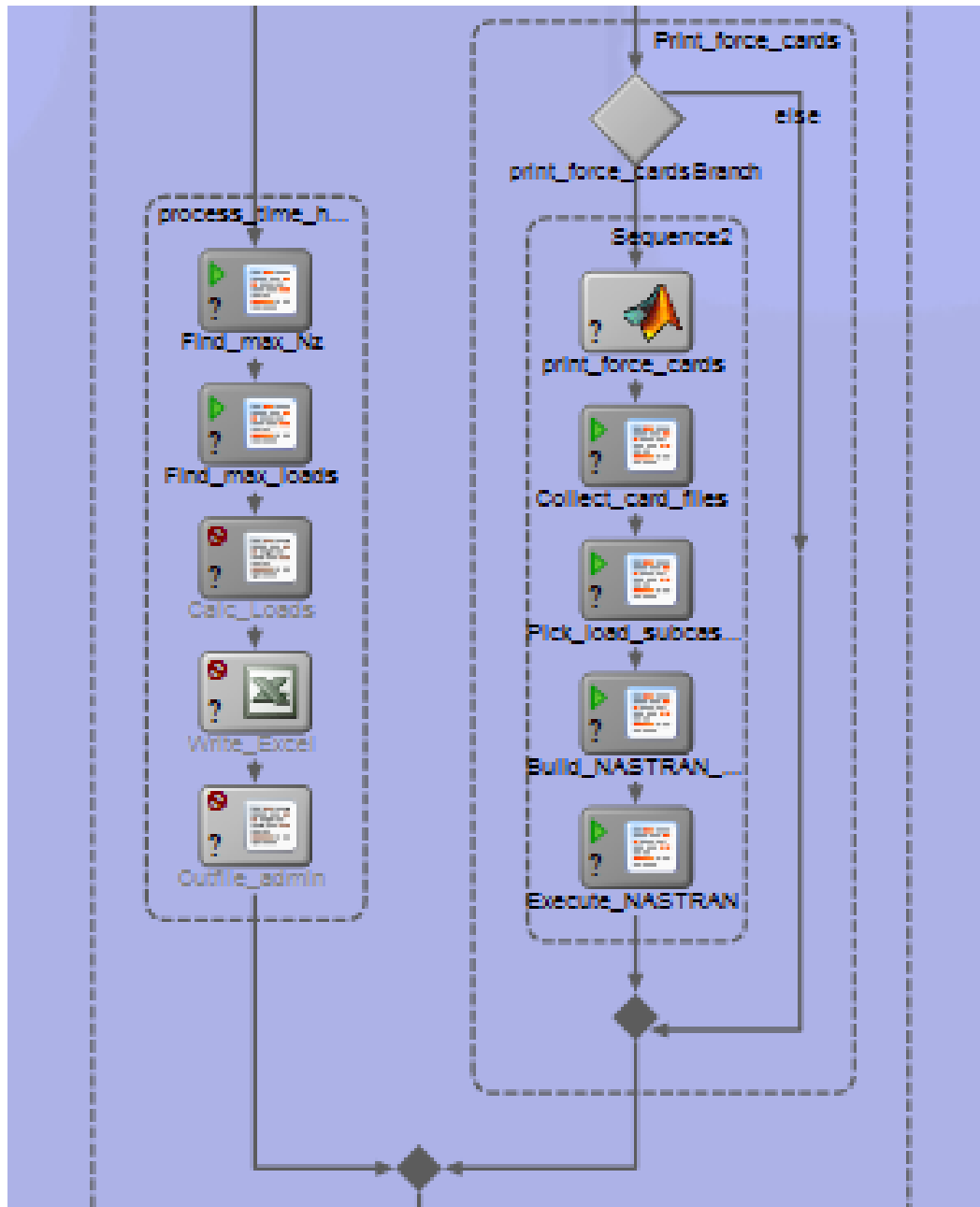
Script

```
1 sub run
2 st3 = st3list (ICFLAG-1)
3 st4 = st3+0.2
4 sf2 = sf2list (ICFLAG-1)
5 sf3 = sf3list (ICFLAG-1)
6 TgtNz = TgtNzlist (ICFLAG-1)
7 end sub
8
```





The Process in Model Center





Conclusions



- StS DFS essentially adds the incremental dynamic aeroelastic loads to the wind tunnel measured loads with or without static aeroelastic correction.
- StS DFS can be modified to import the flight recorded aircraft states for generating loads spectrums of individual fleet members.
- StS DFS can identify previously undefined high stress monitoring areas (hot spots).
- The loads spectrum generated by StS DFS can be used to perform ground fatigue tests or fatigue analysis to identify the residual fatigue life of aircrafts.



Demo

