

Physics-Based Distributed Collaborative Design for Aerospace Vehicle Development and Technology Assessment

**Phoenix Integration
2018 International Users'
Conference
April 17-19, 2018**

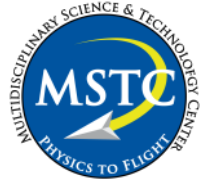


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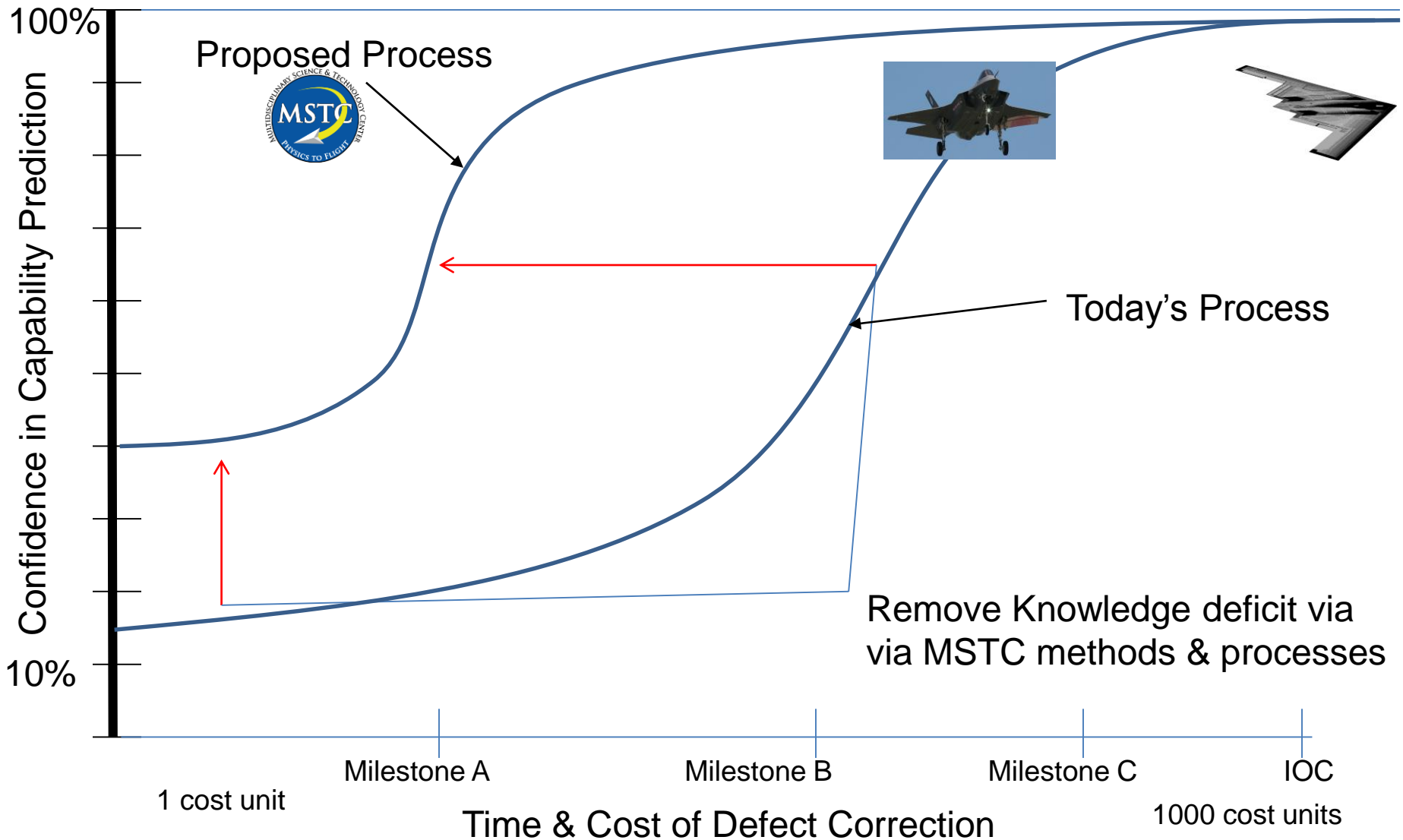




Reducing the Knowledge Deficit in Capability Prediction



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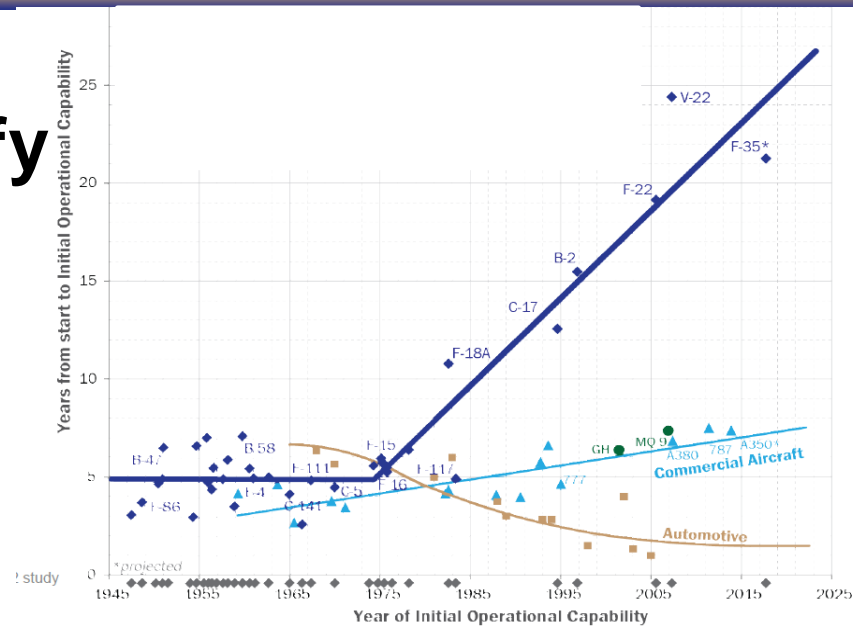


Some Goals



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➤ **Deliver vehicles that satisfy mission requirements in a timely manner**



➤ **Reduce the number of late defects due to unmodeled physics**

➤ **Trace technology to mission level capability impact based on physics – Effectiveness Based Design**



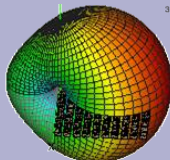
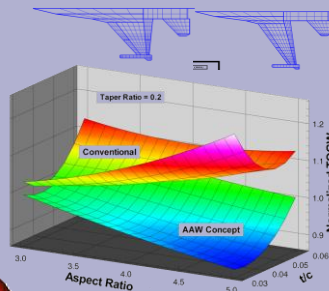
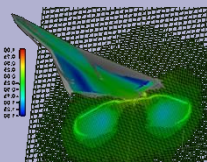
Develop & Trace Technology to Mission Level Capability Impact Based on Physics



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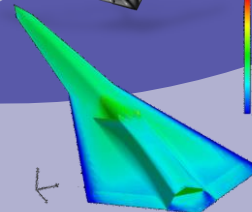
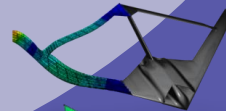
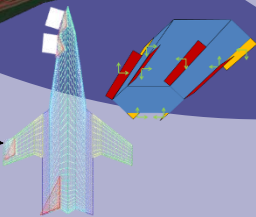
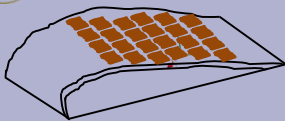
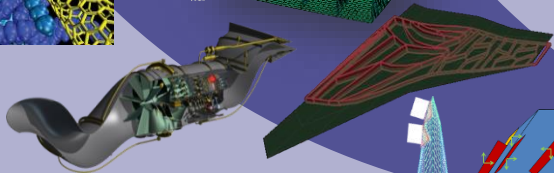
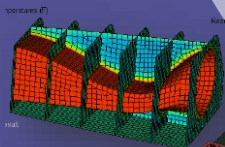
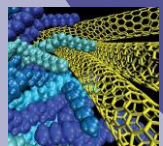
Technology

- Aeroelastic Wing
- Flutter Suppression
- Third Stream Engine
- Advanced Materials
- Thrust Vectoring
- Innovative Control Effectors
- Directed Energy
- Conformal Load Bearing Antennas



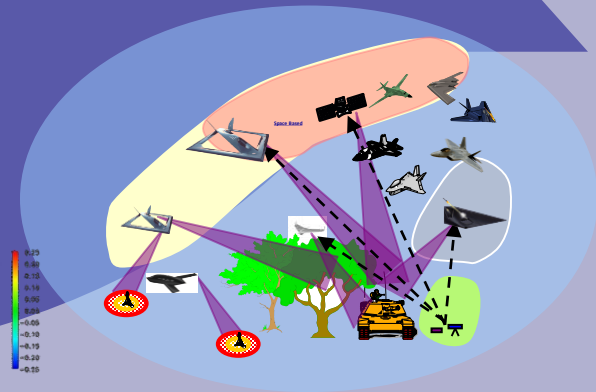
Engineering Capability Impact

- Weight Reduction
- Drag Reduction
- RCS reduction
- Fuel Efficiency
- Roll Performance
- Radar Efficiency



Mission Capability Impact

- Combat effectiveness
- Survivability
- Kills/\$
- IDs/\$
- Maintainability
- Life Cycle Cost
- Sustainability

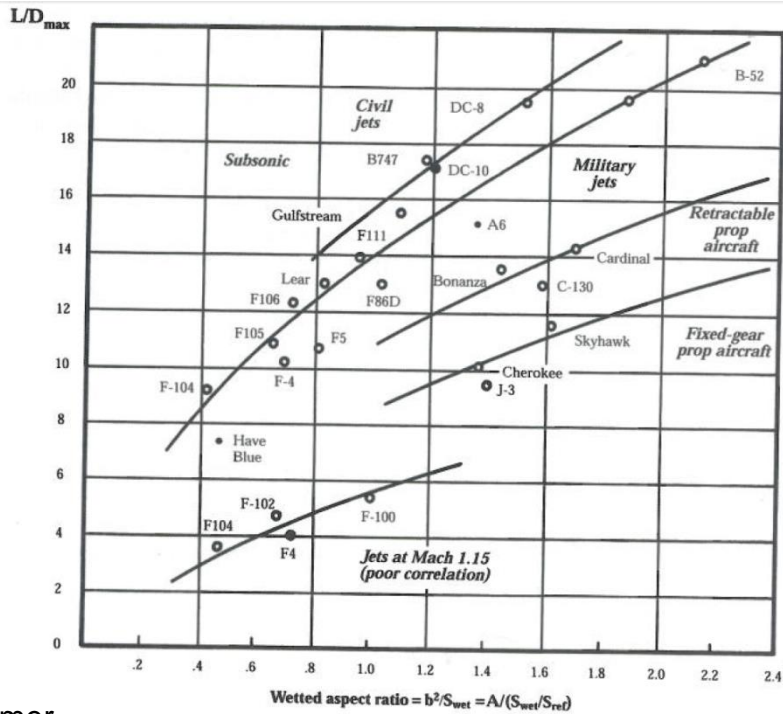


Want to find: $\frac{\partial \text{Mission_Capability}}{\partial \text{Technology}}$

What we mean by “Physics Based”

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Regressions of historical Data

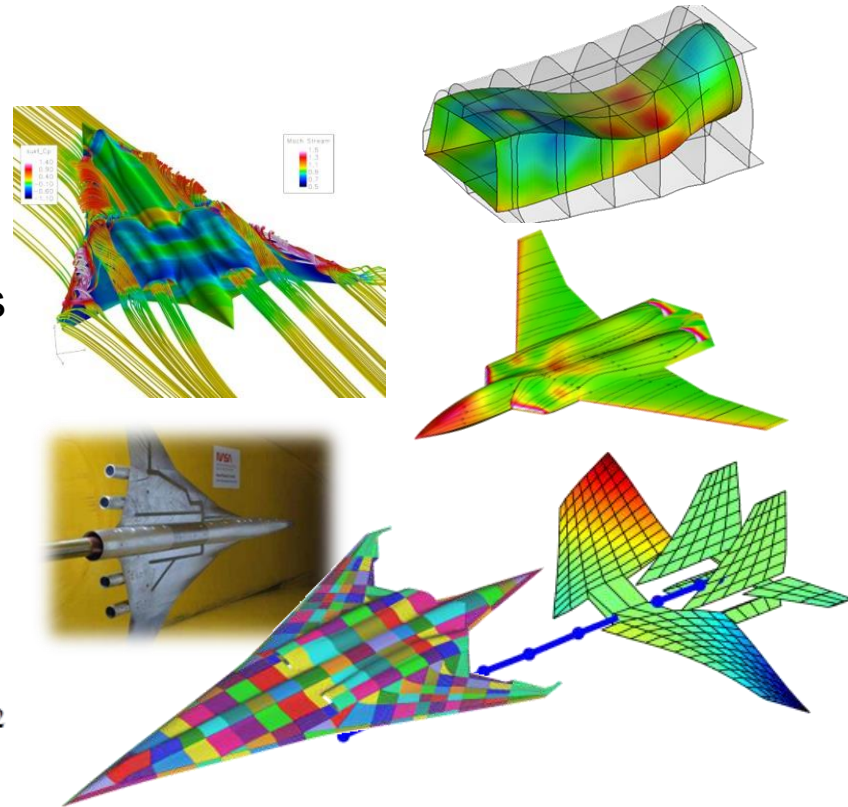


Raymer

$$W_{wing} = (k_{tech_factor}) * 0.0103 K_{dw} K_{vs} (W_{dg} N_z)^{0.5} S_w^{0.622} * A^{0.785} (t/c)_{root}^{-0.04} (1 + \lambda)^{0.05} (\cos \lambda)^{-1} S_{CSW}^{0.04}$$

Computational or testing on actual configuration

Versus



Historical data insufficient for designing new/innovative configurations and assessing new technologies

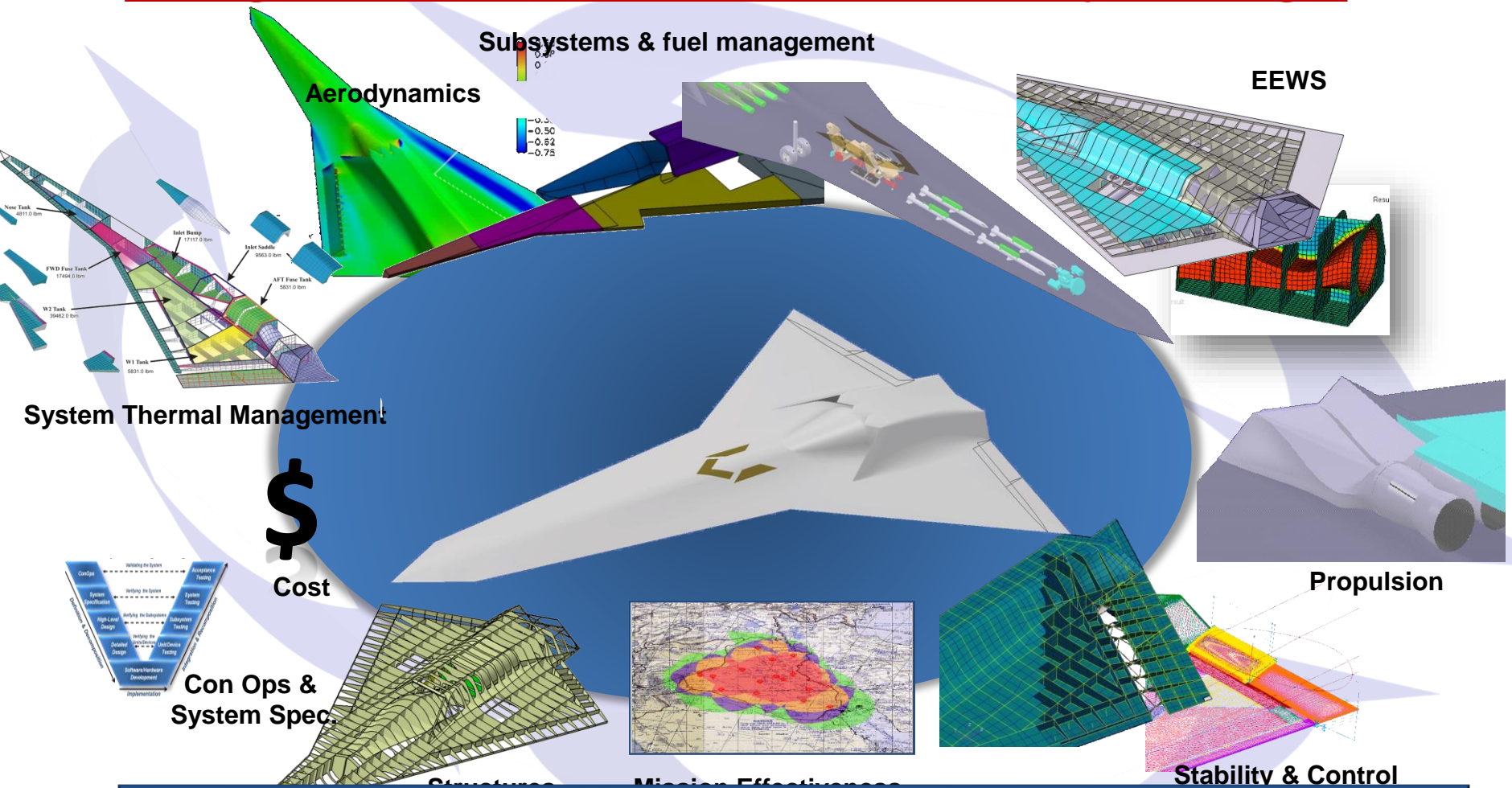


MSTC Design Process Goals (System Level Multi-Fidelity MADO)



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Merge Conceptual & Preliminary Design



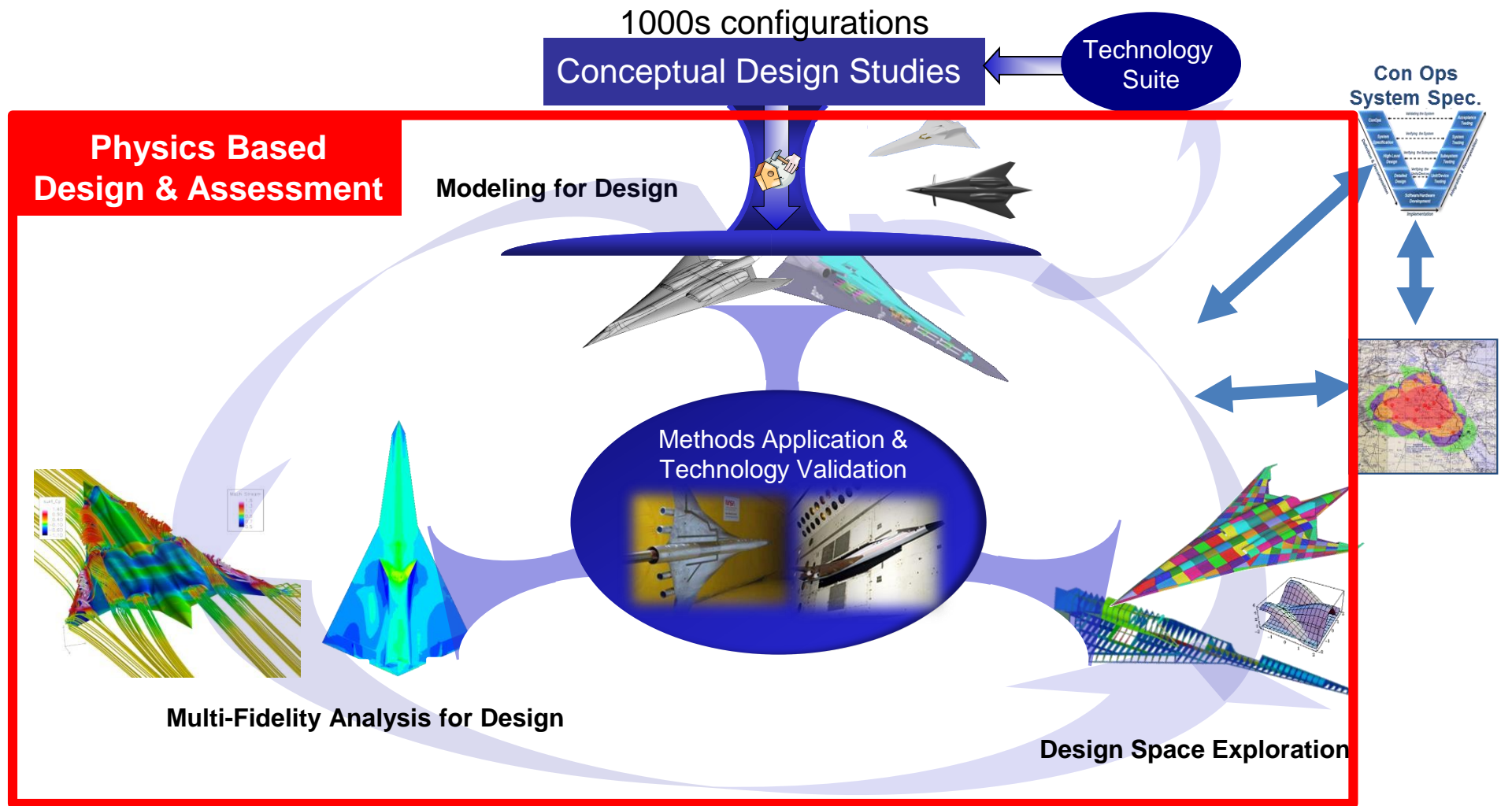
Add Disciplines, Couplings, & Fidelity - Early



How to Capture the Physics Driving the Design Pre-Milestone A



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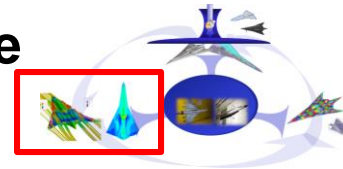
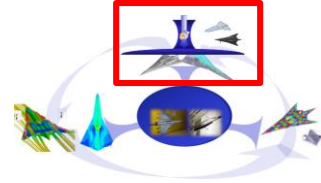
Get more (and Better) Information ... and get it Earlier



Gaps to Achieving Desired Process



- Need rapid development of domain model construction from geometry (structural lay-outs, configurations, FEM, CFD Meshes, sub-systems etc..)
- Need coupling of all necessary engineering disciplines (structures, aero, thermal, controls, acoustics etc..) at the appropriate level of fidelity to predict static and dynamic responses
- **Computational framework that supports hi-fidelity distributed collaborative design.**
- Synthesis process does not currently include uncertainty & probabilistic design methods
- Culture



Need to be able to do 10's of HiFi Physics Based Configuration Design with the Same Resources & Time of Traditional Conceptual Design



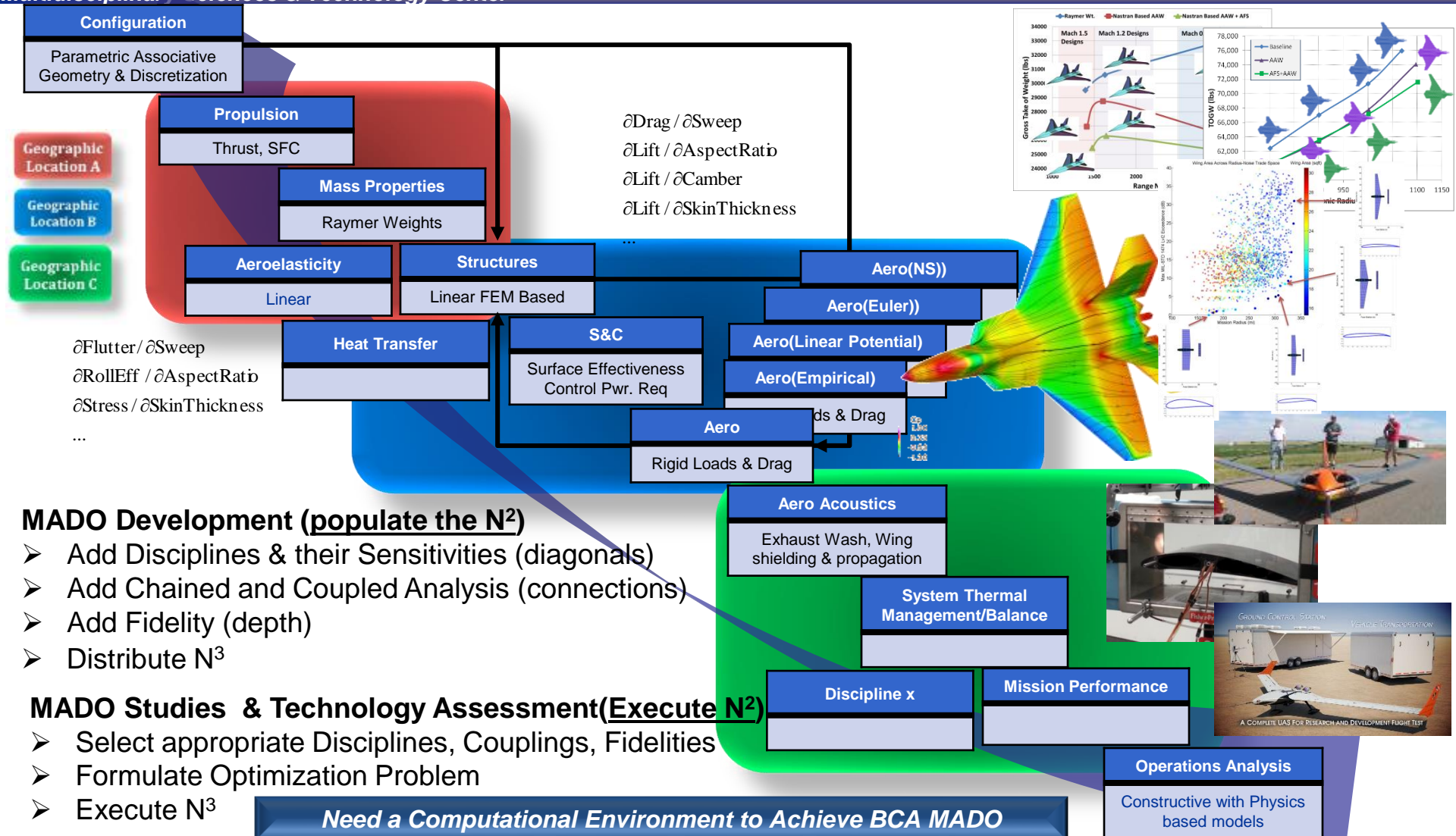
MADO N³ Diagram

(aka design structure matrix, dependency structure matrix, spider diagram)

MSTC Develops, Executes & Validates



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MADO Development (populate the N²)

- Add Disciplines & their Sensitivities (diagonals)
- Add Chained and Coupled Analysis (connections)
- Add Fidelity (depth)
- Distribute N³

MADO Studies & Technology Assessment (Execute N²)

- Select appropriate Disciplines, Couplings, Fidelities
- Formulate Optimization Problem
- Execute N³

MD Technology Validation (Validate results of N² Execution)

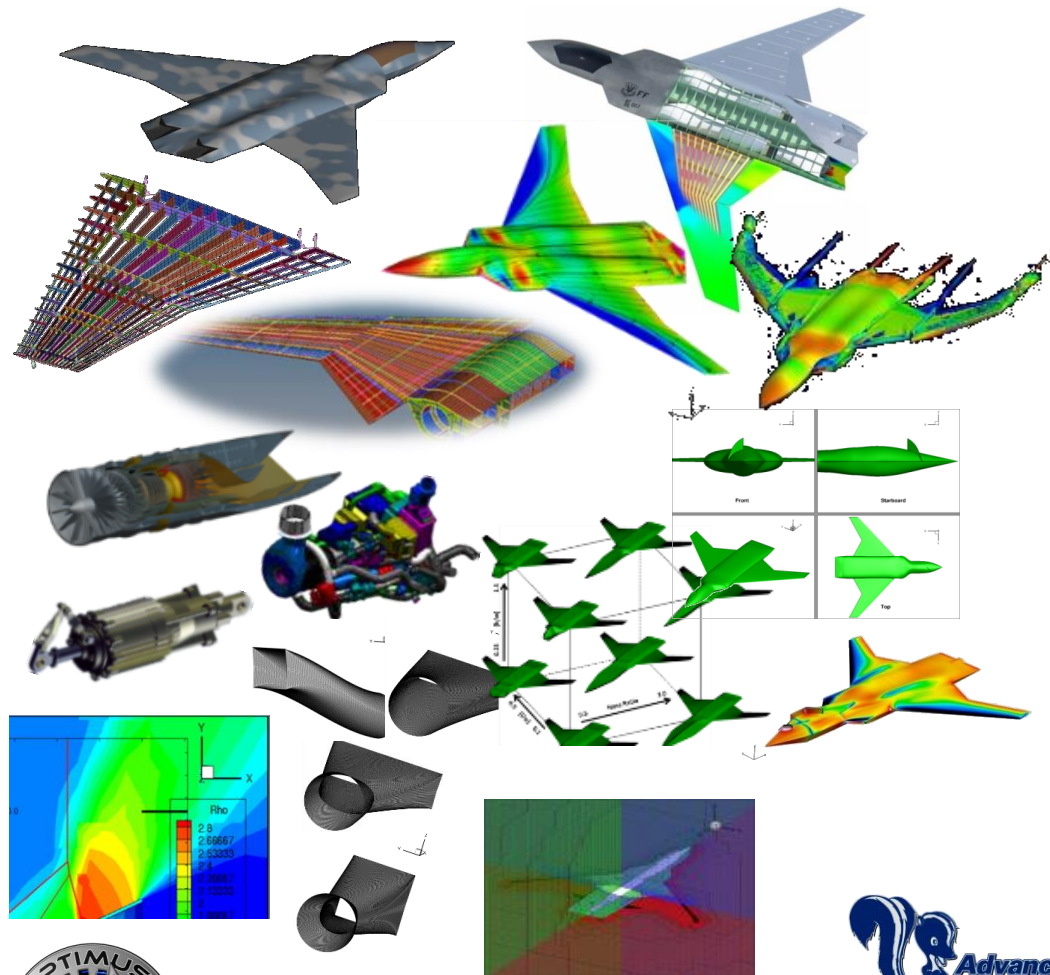
- Ground, Wind tunnel & Flight Experiments



Typical Target Application Efficient Supersonic Configuration



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Effectiveness Objectives

Access, Firepower, Reach, Speed/Agility

Engineering Objectives

Range, Weight, Specific Excess Power

Design Variables

- Aerodynamic (10's)
- Controls (10's)
- Engine (10's)
- Subsystems (100's)
- Structural (1000's)

Constraints

- Strength, Stiffness, Thermal
- Static and Dynamic Aeroelastic
- Level 1-3 Fidelity

Technology Evaluations

- Configuration
 - Compact Weapons,
 - Compact Launchers
- Aerodynamics
 - Subsonic Laminar Flow ,
 - Supersonic Laminar Flow
- Propulsion
 - Variable Cycle Engine
 - Advanced High Speed Inlet
- Structures
 - Active Aeroelastic Wing
 - Active Flutter Suppression
- S & C
 - ICE Effectors (SSD)



Boeing

Northrop
ESAVE



ESAVE, EXPEDITE



MSTC High Level Requirements for System Level MADO (MDMFMSAOWUQ)



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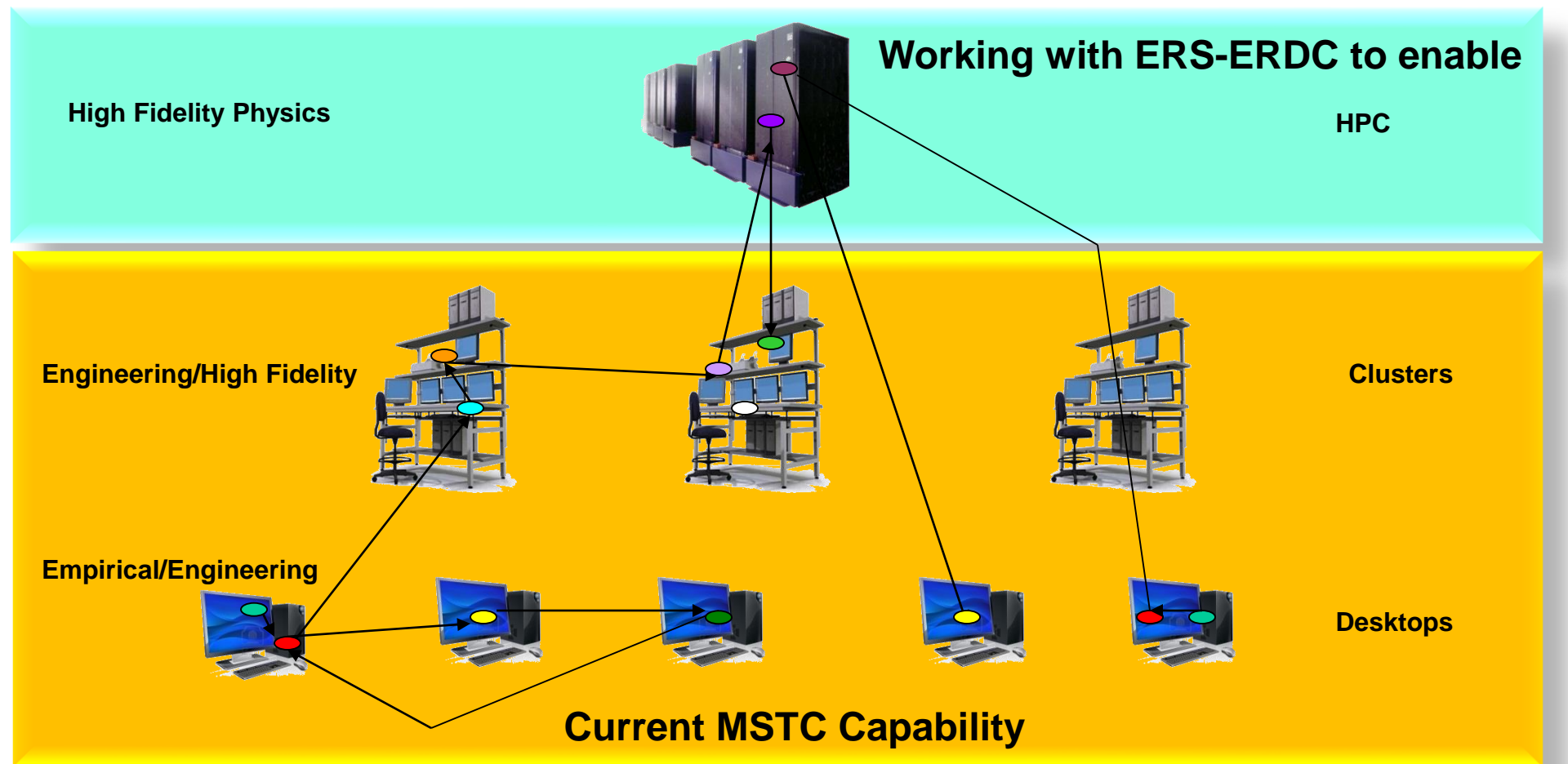
- # of components/applications/Services – 100's to 1000's
- Run times of services – secs to weeks
- Data
 - ✦ kilobytes to terabytes
 - ✦ ascii, binary, databases
- Distributed (across organizational boundaries) heterogeneous computing environment
 - ✦ Hand held devices to HPC resources
 - ✦ Seamless access to data and services
 - ✦ Process representation with secure communications
- 1E4 of design variables
- 1E5 constraints
- Multi-Objective



Physics Based Distributed Collaborative Design (Compute Resource View)



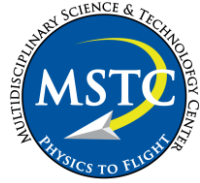
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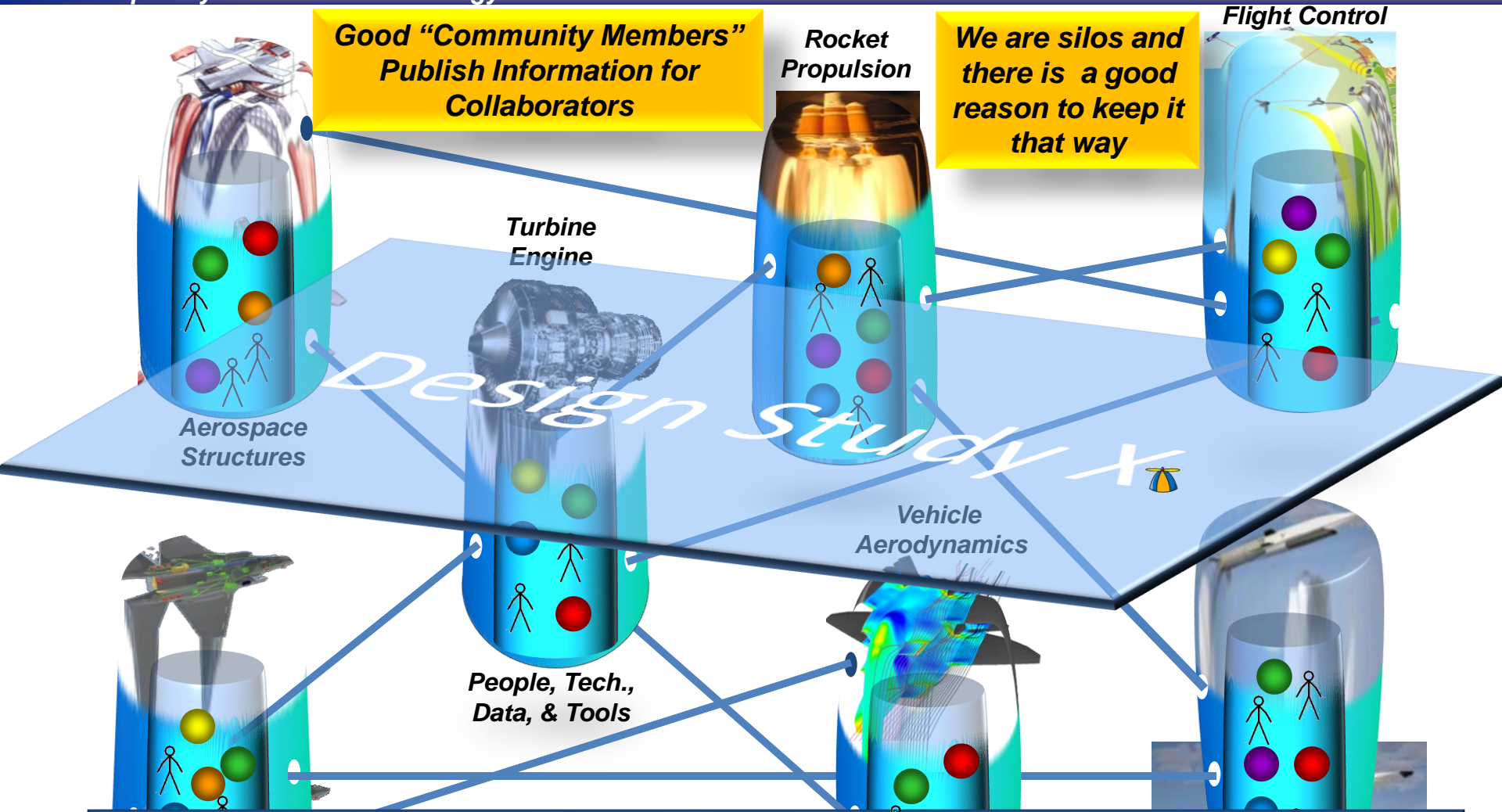
Seamless Access to All Methods, Models, Data, and Compute Resources Across the Network



Physics Based Distributed Collaborative Design (Org View)



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As Needed Real Time Access to Applications & Data by ALL Communities Distributed Collaborative Design!



Impact



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Scientific Impact

Past



Exploiting the **synergism** of mutually interacting phenomena to **produce a capability that cannot be obtained otherwise**

Future



Multi-disciplinary Science is an **enabler** for the development of the next generation air and space vehicles

Acquisition Impact

Reduce discovery of late defects due to un-modeled physics



It is essential to determine early on the pertinent interactions between coupled engineering disciplines

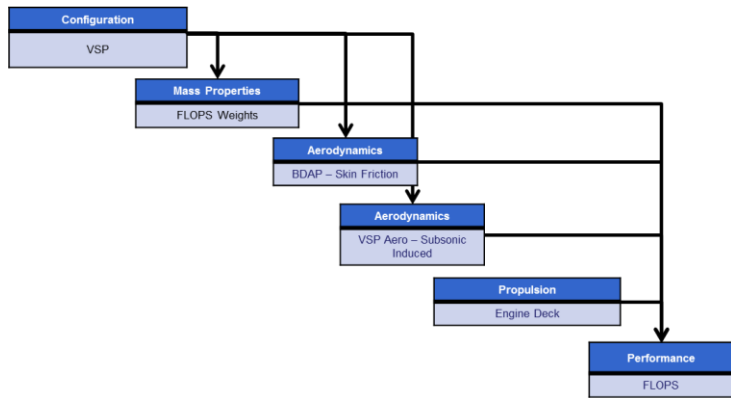
Small UAV Design

Without Distributed Collaborative Design (RQVA)



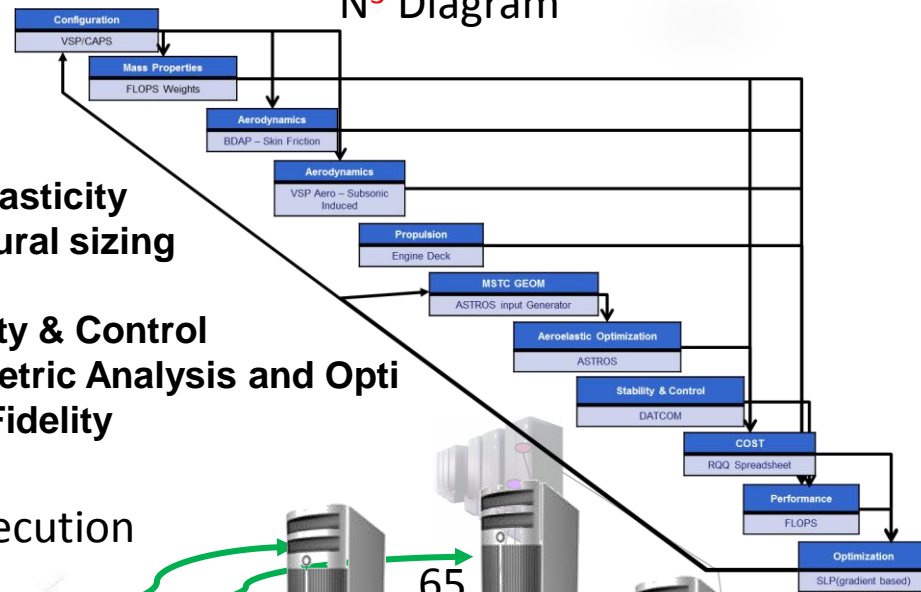
RQVA

N² Diagram



Design With Collaborative Distributed Design (RQVA, RQVC, RQQ, RQT)

N³ Diagram



- Aeroelasticity
- Structural sizing
- Cost
- Stability & Control
- Parametric Analysis and Opti
- Multi-Fidelity

N² Diagram Execution



24C

N³ Diagram Execution



24C

200X –throughput demonstrated to date.

65, 146, 65, 146, 65

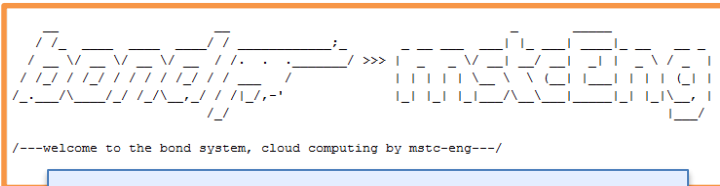
Significant Cultural Change - Gives More Information, Faster – Better Decisions



Small UAV Design Study with MSCT-Engineering

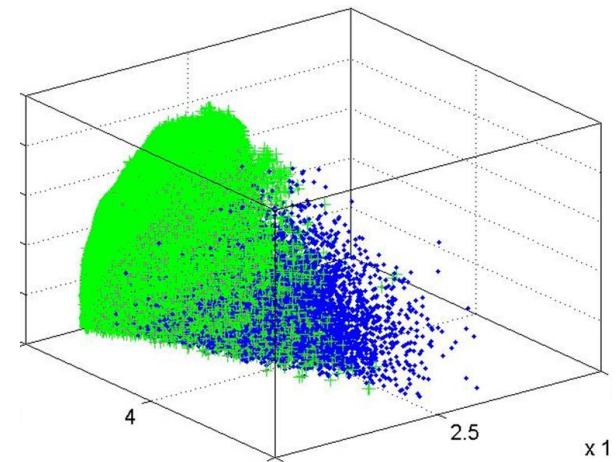
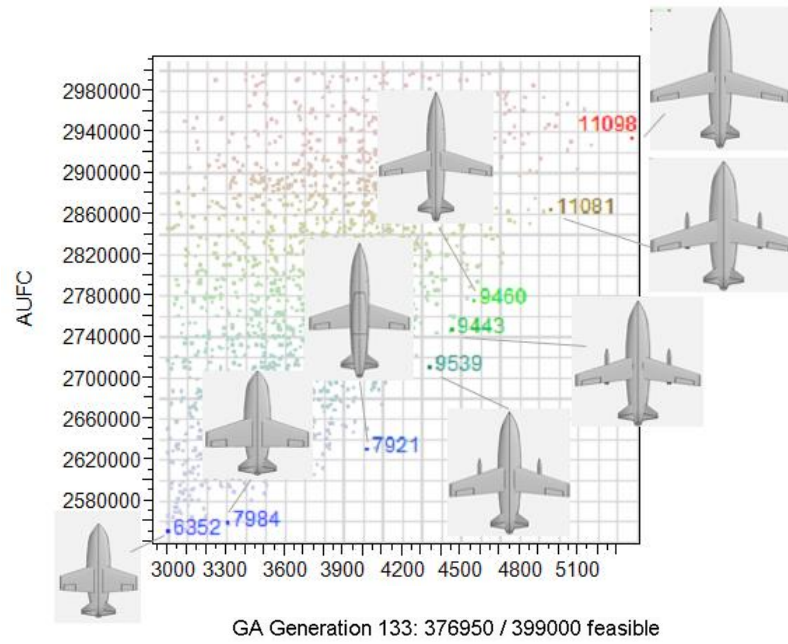


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/---welcome to the bond system, cloud computing by mstc-eng---/

- **MSTC-Eng Environment**
 - ✦ ~26 MSTC-Eng Providers
 - ✦ ~10 Windows Workstations / ~16
 - ✦ ~520 workers
 - ✦ Avg thrupt ~1.75 sec/run (avg run ~7min)
- **Multiobjective Genetic Algorithm:** gamultiobj (variant NSGA-II)
- **Three objectives:** min AUFC, max range, max tacAvgAlt
- **Nine design variables:** 'wingSpan1', 'wingSweep1', 'wingArea', 'wingTaper', 'fuseLength', 'fuseWidth', 'timeOnStation', 'cruiseMach', 'loiterMach'
- **Constants:**
- **GA Parameters**
 - ✦ Population: 3000
 - ✦ Generations: 135
 - ✦ Total runs: 400k



Results courtesy Burton, White, Kao and team



Small UAV Design Study with MSCT-Engineering



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gaMovie_8Gen.mp4



Some Future Technologies that will impact Aerospace Vehicle Design



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➤ **Modeling for design**

- ✦ Rapid Attributed, associative parametric OML & IML with geometric sensitivities
- ✦ Human machine interface to design process/environments (VR)
 - ▲ Ironman JARVIS (Just a Rather Very Intelligent System)
 - ▲ Minority report

➤ **Analysis for design**

- ✦ Mathematize selection of disciplines & couplings based on decisions being made
- ✦ Multi-scale multi-fidelity analysis & sensitivities
- ✦ System of systems

➤ **Design Space Exploration**

- ✦ Additive Manufacture
- ✦ Multi-scale Optimization (topology optimization)
- ✦ Faster to 3D print & test then create computational models?
- ✦ Big data – database technology, search algorithms (achieve every run)
- ✦ Distributed Collaborative Design (multi-tier vendor participation)

➤ **Computation Resources**

- ✦ Cloud
- ✦ Security

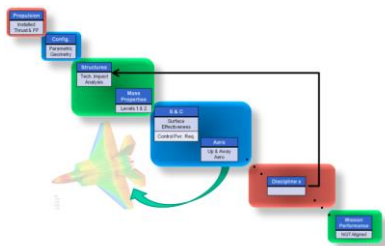


Concluding Remarks

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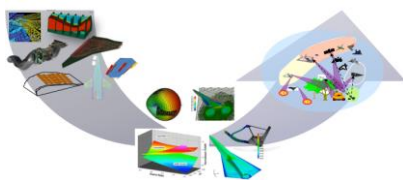
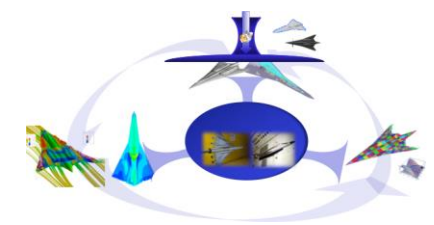


➤ **Historical data & traditional conceptual design processes are insufficient for designing new/innovative configurations and technologies**



➤ **A physics-based distributed collaborative design Environment for aerospace vehicle development and technology assessment has been developed (leverages MSTC Engineering)**

➤ **Enables 10's of HiFi Physics Based Configuration Design with the Same Resources & Time of Traditional Design evaluates 1 or 2.**

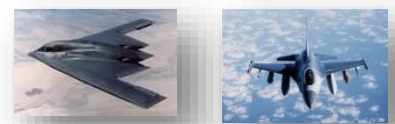


➤ **Enables AFRL technology developers to have a quantifiable, physics based and traceable trail of the impact of their technologies on system effectiveness - lethality, survivability, sustainability, affordability etc...**



➤ **Creates info. with less uncertainty for making decisions for system capabilities, technology assessment, and technology risk reduction**

➤ **Reduction of late Defects due to physics**



If you can change the culture, everything else is "easy"



Thank you!

Questions?



Some Closing Thoughts



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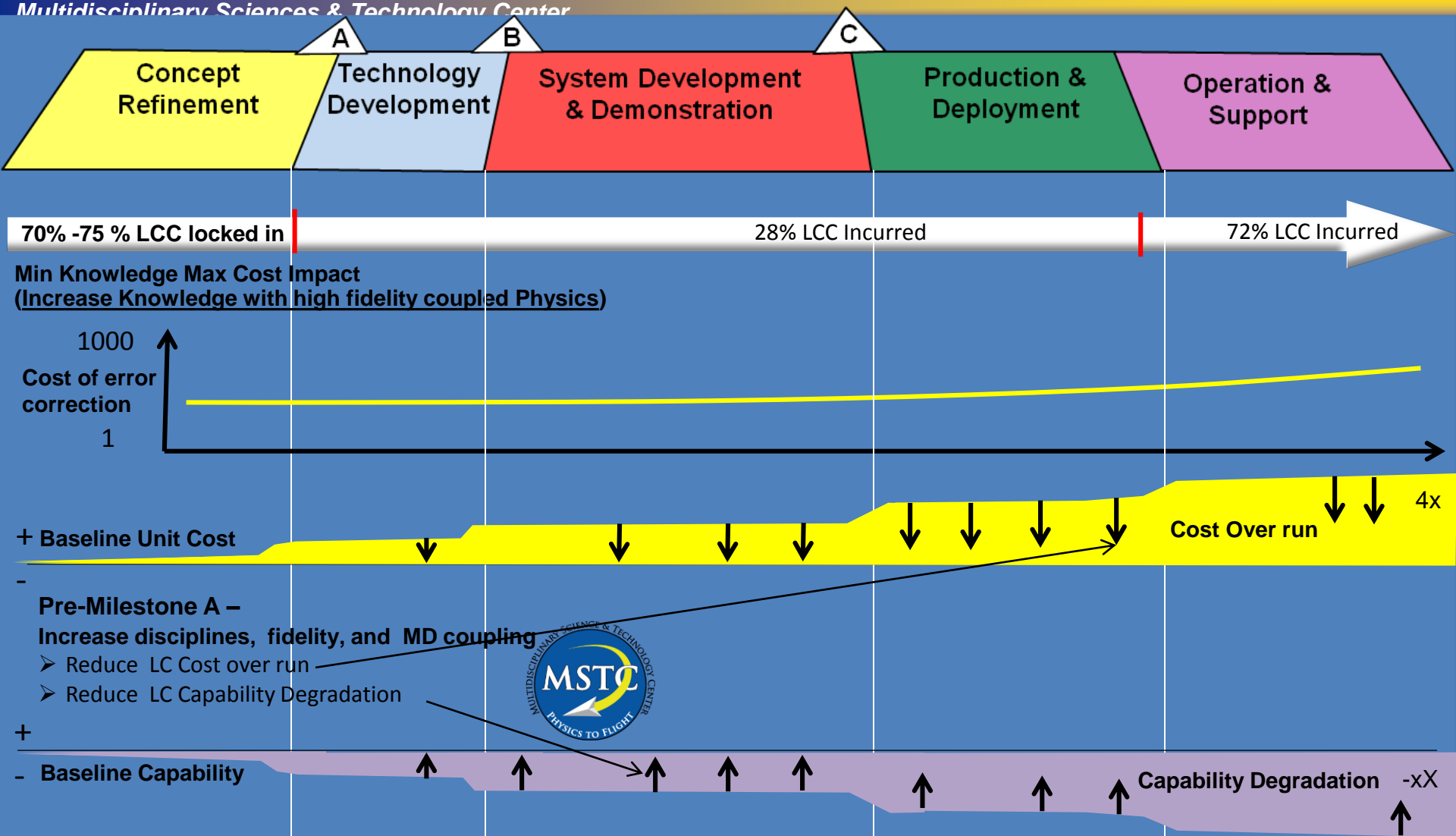
- *If you can change the culture, everything else is “easy”*
- ***Very often, today’s experts achieved their accomplishments by doing what the previous generation experts said should or could not be done.***
- *Significant Investment Still Needed – Substantial ROI Available*



Cost & Capability versus Life Cycle



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Driving High Fidelity Physics Based Design Early in the Process Produces More Capability & Lower Cost Over Life Cycle (“Bend the Cost Curve”)

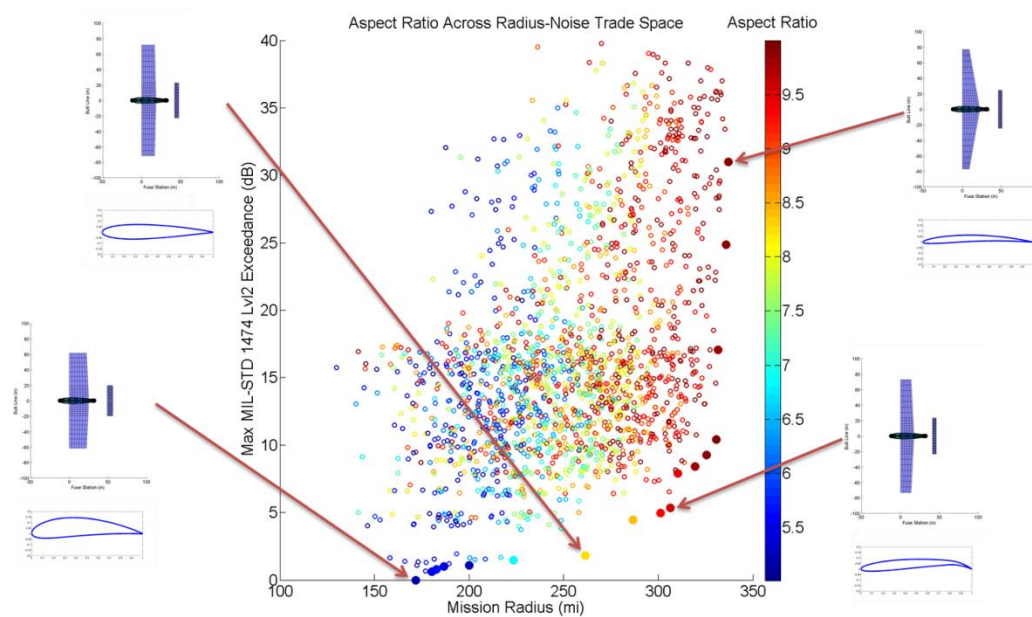
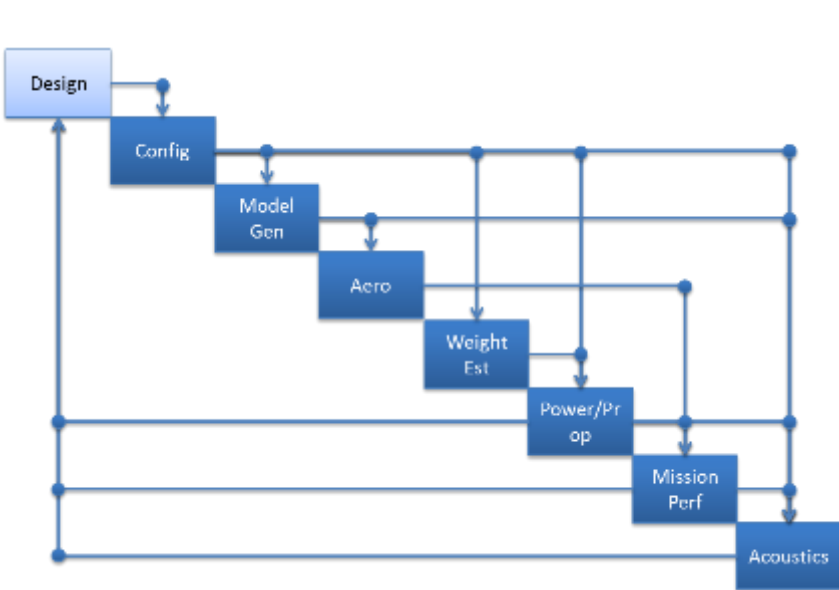


Small UAV Design Study with MSTC-Engineering



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- Design of vehicle for minimum airframe noise
 - ✦ Vary area, aspect ratio, taper ratio, airfoil (NACA 4-digit), loiter speed
- Maximize mission radius while minimizing noise
- Produced viable designs and design guidance for customer
- Developed distributed design process in MSTC-Eng.
- Solved with GA – 10^5 runs



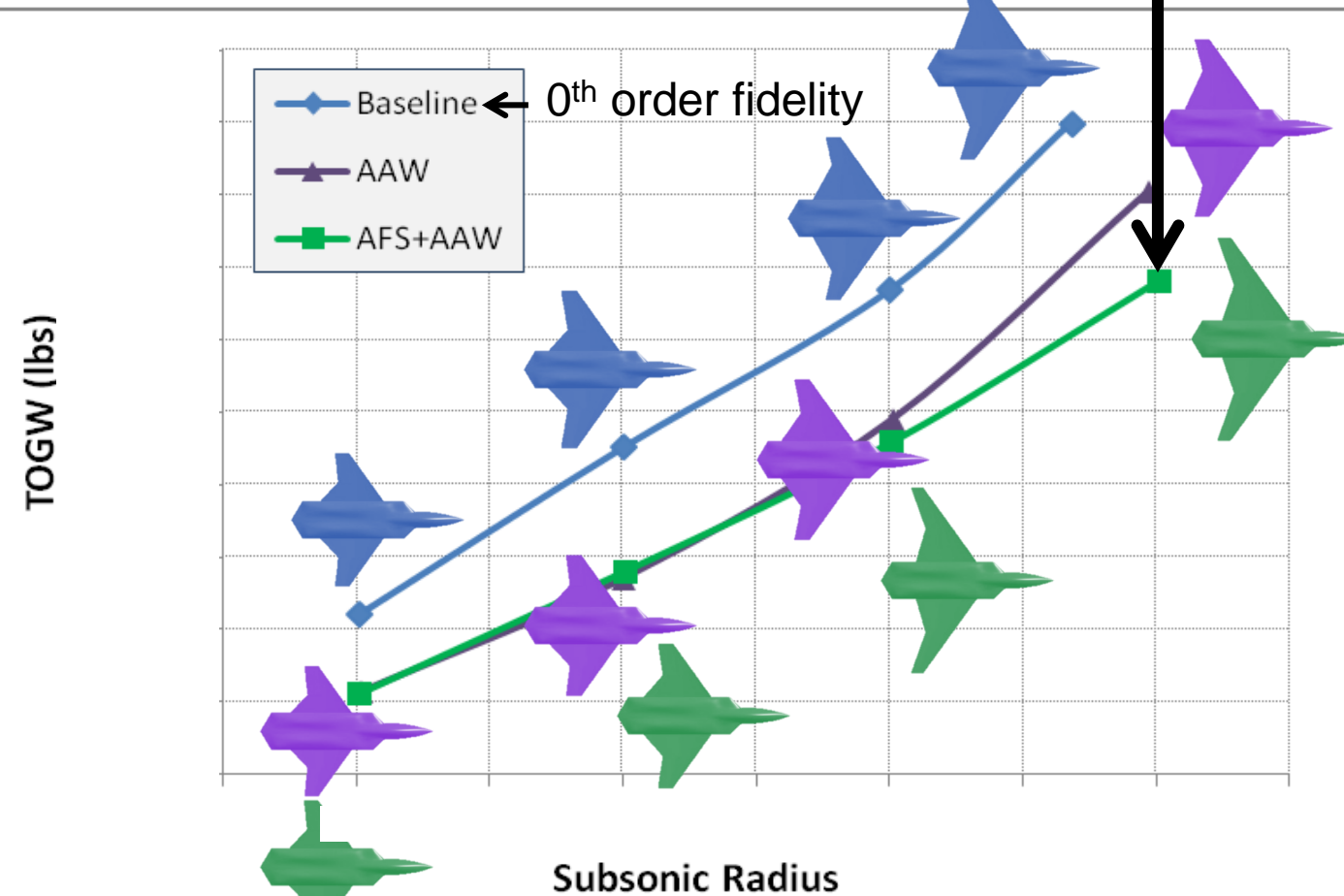


Impact on Efficient Supersonic Air Vehicle Design & Technology Assessment



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← ≠ 0.6% Empty Wt



Using traditional Level 0 Conceptual Design
- Active flutter suppression benefit 0.6% Empty Wt



Increasing Physics Disciplines & Coupling has a Significant Impact on the Resulting Vehicle Configuration, Performance, & Technology Impact